



University of Colorado



Boulder



Snow Data Assimilation via an Ensemble Kalman Filter

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Uncertainty in Numerical Modeling

(1) Model Structure

- Parameterizations
- Piecing together components
- Numerical methods

(2) Model Forcing

- Spatial & Temporal structure

(3) Parameter Data

- Soils & Vegetation, type and distribution

(4) Initial Conditions

- Influences trajectory (forecasting = IVP)

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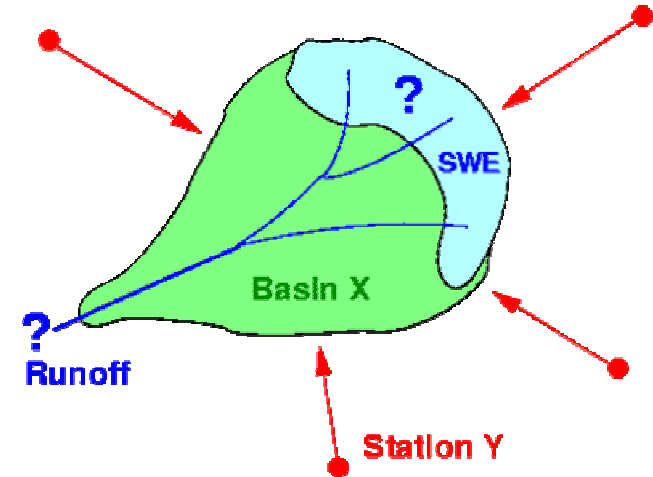
- Soils & Vegetation, type and distribution

(4) Initial Conditions

- Influences trajectory (forecasting = IVP)

Snow Assimilation & Hydro Forecasting

- Snowpack has big impact
- Sub-optimal data cover



- **Aim** : best estimate of SWE initial conditions for streamflow prediction by combining models & observations
- **Research philosophy**
 - Calibration solves low frequency variability
 - Assimilation aids high frequency variability

Data Assimilation : Ensemble Kalman Filter

$$1. \mathbf{X}_t^- = \mathbf{A}\mathbf{X}_{t-1} + \mathbf{B}\mathbf{f}_t$$

$$2. \mathbf{K}_t = \mathbf{P}_t \mathbf{H}^T (\mathbf{H} \mathbf{P}_t \mathbf{H}^T + \mathbf{R})^{-1}$$

$$3. \mathbf{X}_t = \mathbf{X}_t^- + \mathbf{K}_t (\mathbf{z}_t - \mathbf{H}\mathbf{X}_t^-)$$

1. Project model state (\mathbf{X}) forward as a function of last model state ($\mathbf{A}\mathbf{X}_{t-1}$) and the forcing ($\mathbf{B}\mathbf{f}_t$)
2. Compute a Kalman Gain (\mathbf{K}) from covariances (\mathbf{P}) of transformed (\mathbf{H}) model data and observation variance (\mathbf{R}) across ensemble
3. Update the model states using the gain and observations (\mathbf{z})

Stochastic SNOW-17 Simulations

- SNOW-17
 - Anderson (1973)
 - Conceptual model – needs only Temp. + Precip.
 - Runs *operationally* @ the NWS
 - Parameters : CBRFC operational code
 - Calibrated for streamflow, not SWE
 - Nine state variables used
- Model forced with ensemble of inputs

Uncertainties in model inputs (method)

(2-km grid—150 x 150 pixels)

Need estimate of
Precip. and Temp. at
each basin/box/point

PLUS

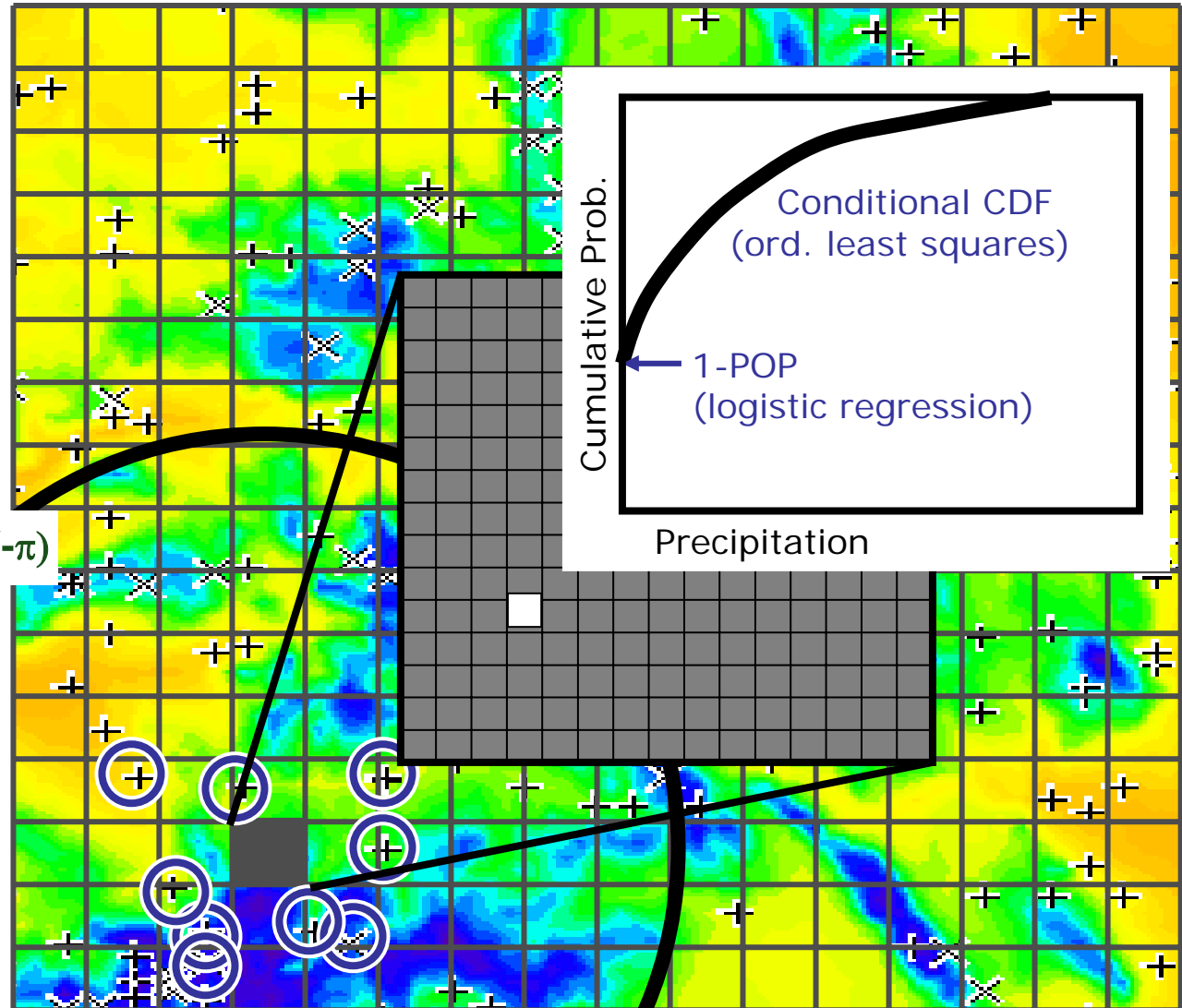
Error estimate

Occurrence:

$$\beta_{\text{new}} = \beta_{\text{old}} + (\mathbf{X}^T \mathbf{W} \mathbf{V} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{W} (\mathbf{Y} - \pi)$$

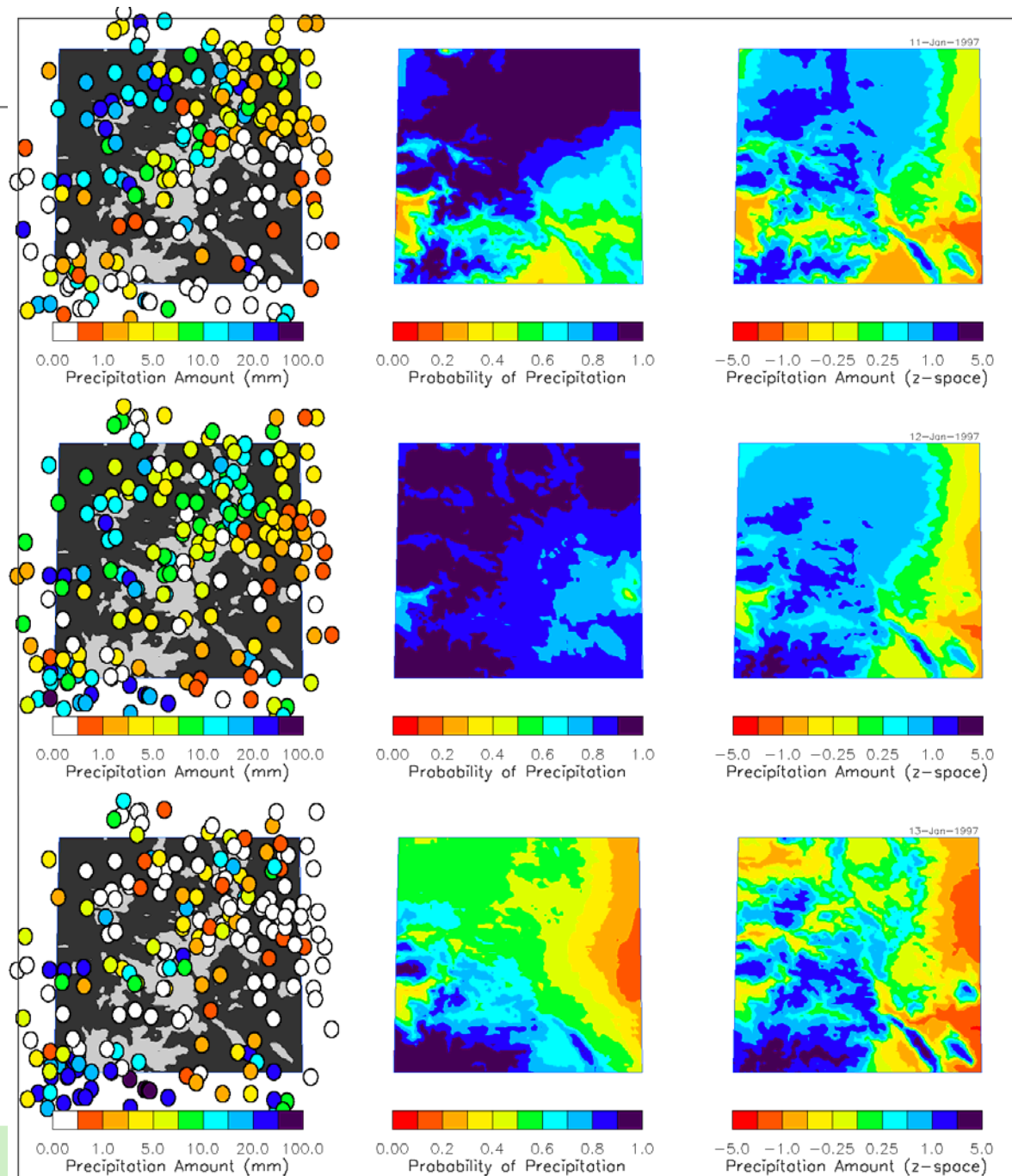
Amounts:

$$\beta = (\mathbf{X}^T \mathbf{W} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{W} \mathbf{Y}$$



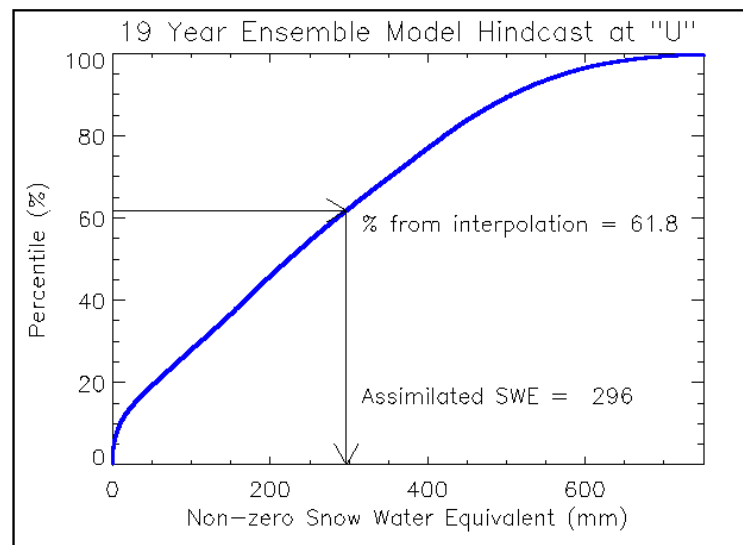
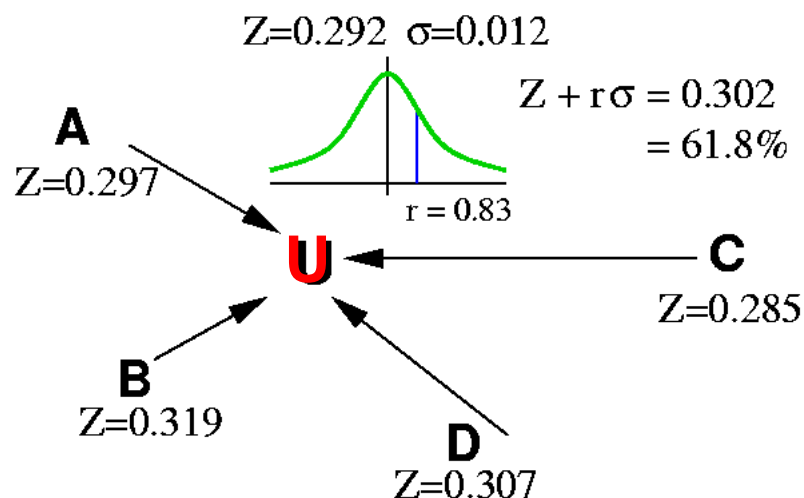
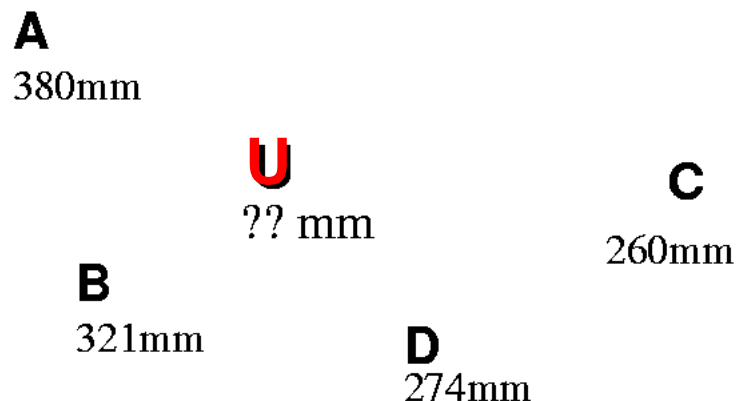
POP & PCP

- Location: Colorado
- Applied Logistic & OLS regression
- All estimates are locally-weighted
- SWE computed similarly
- Temp uses OLS



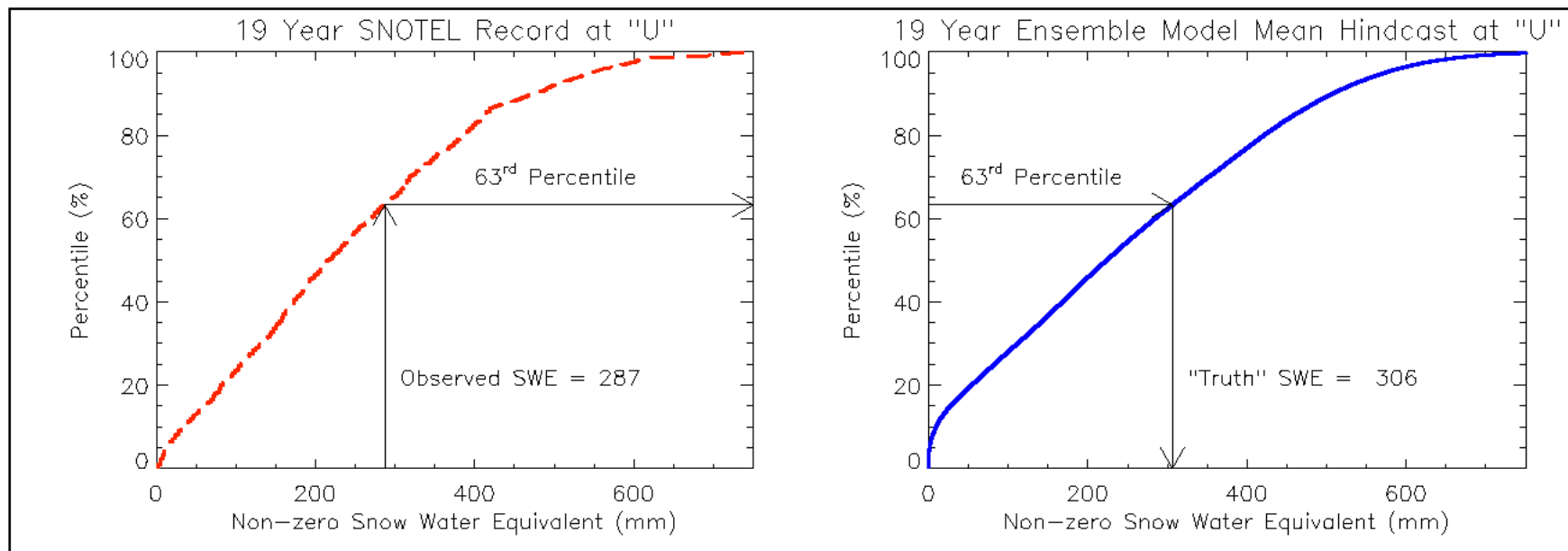
Obtaining Assimilation Data

- 1D EnKF needs data everywhere
- Convert SWE_{obs} to Z-score
- Interpolate & cross validate
- Get SWE_{mod} via model hindcast
- Model-space, unbiased value

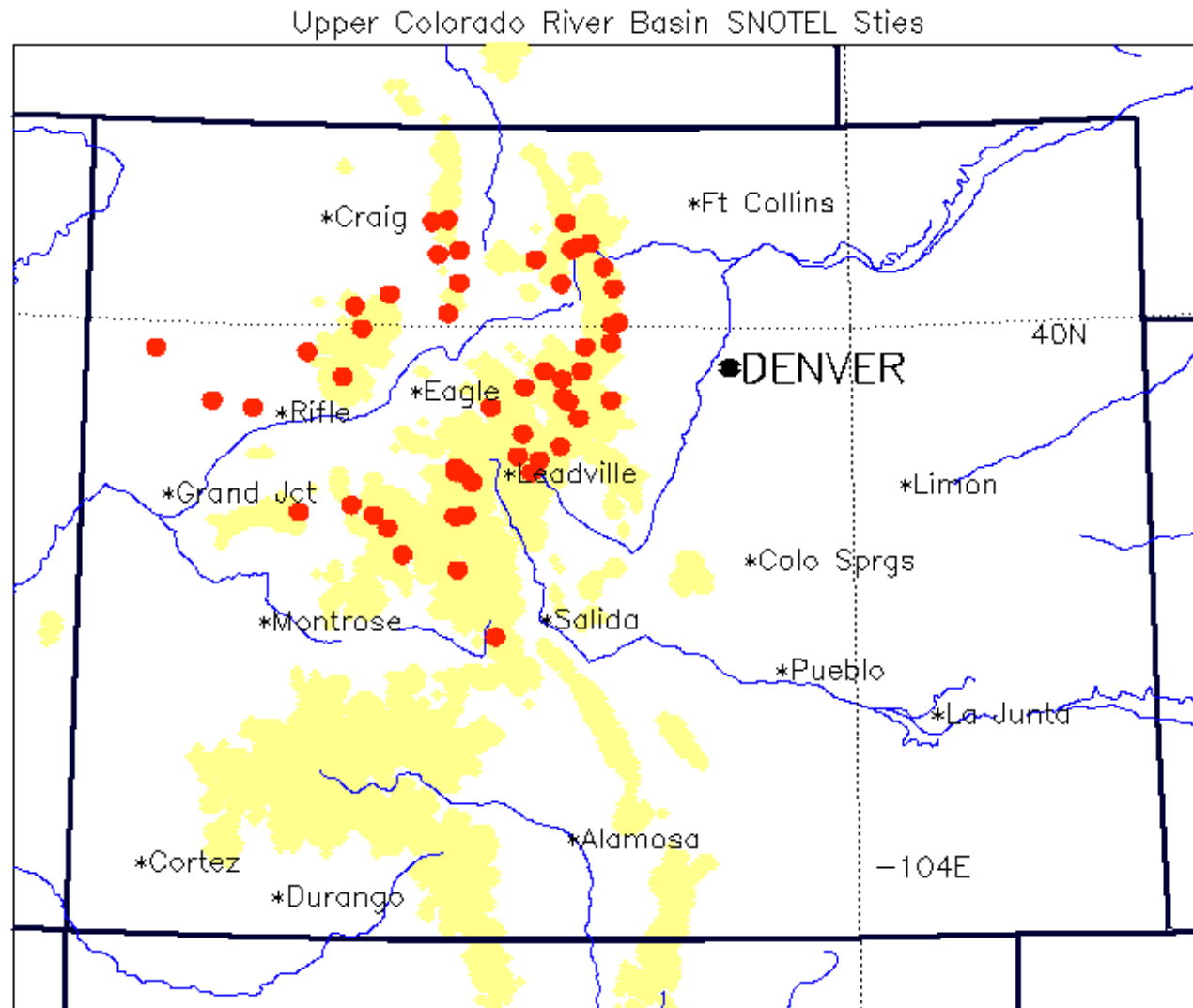


Obtaining “Truth”

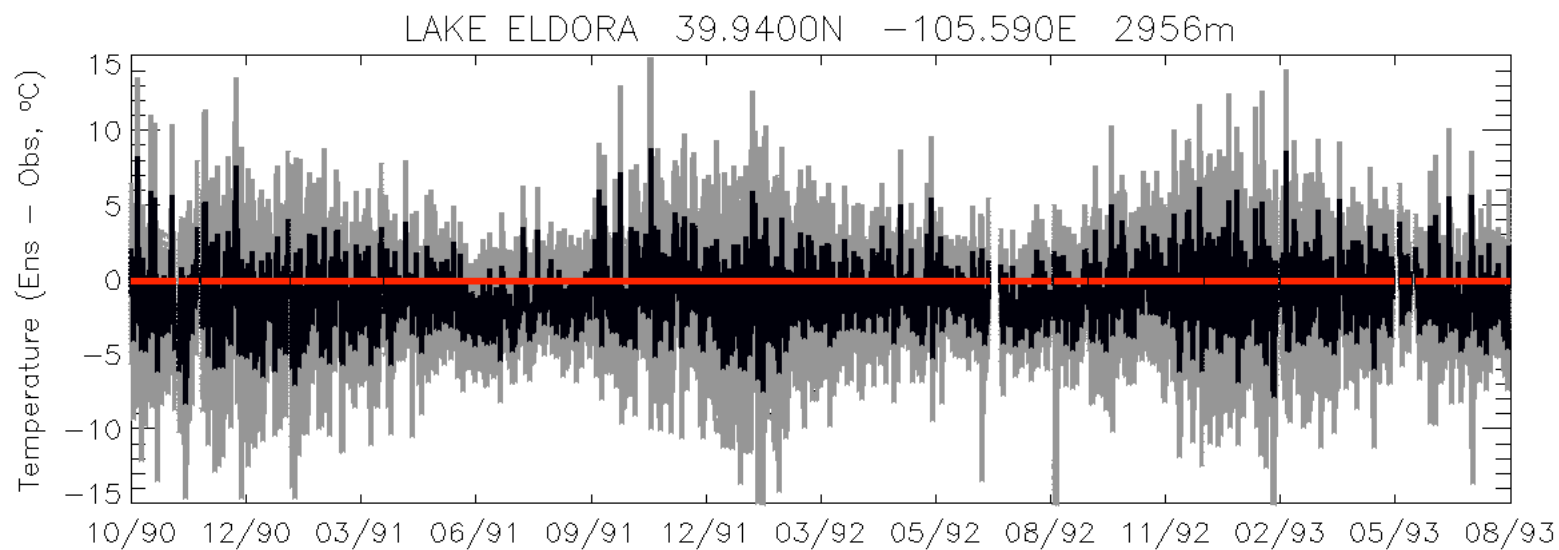
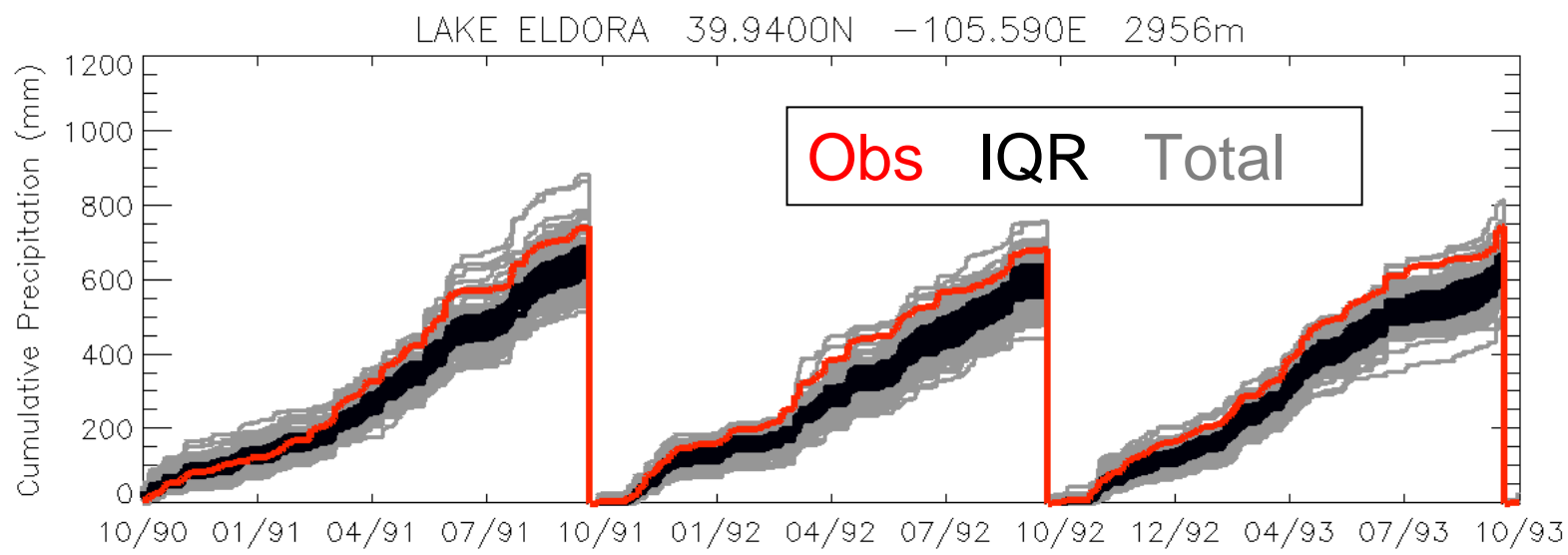
- Model-space equivalent of observed SWE
- Match the non-zero SWE CDF's



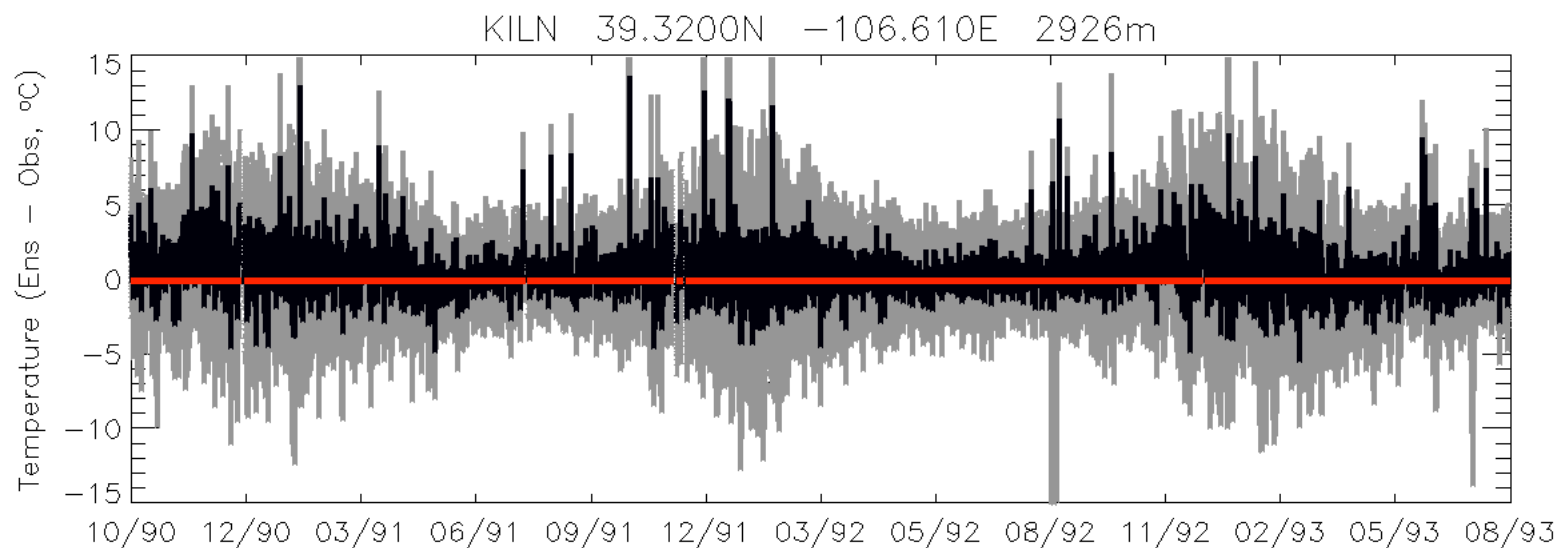
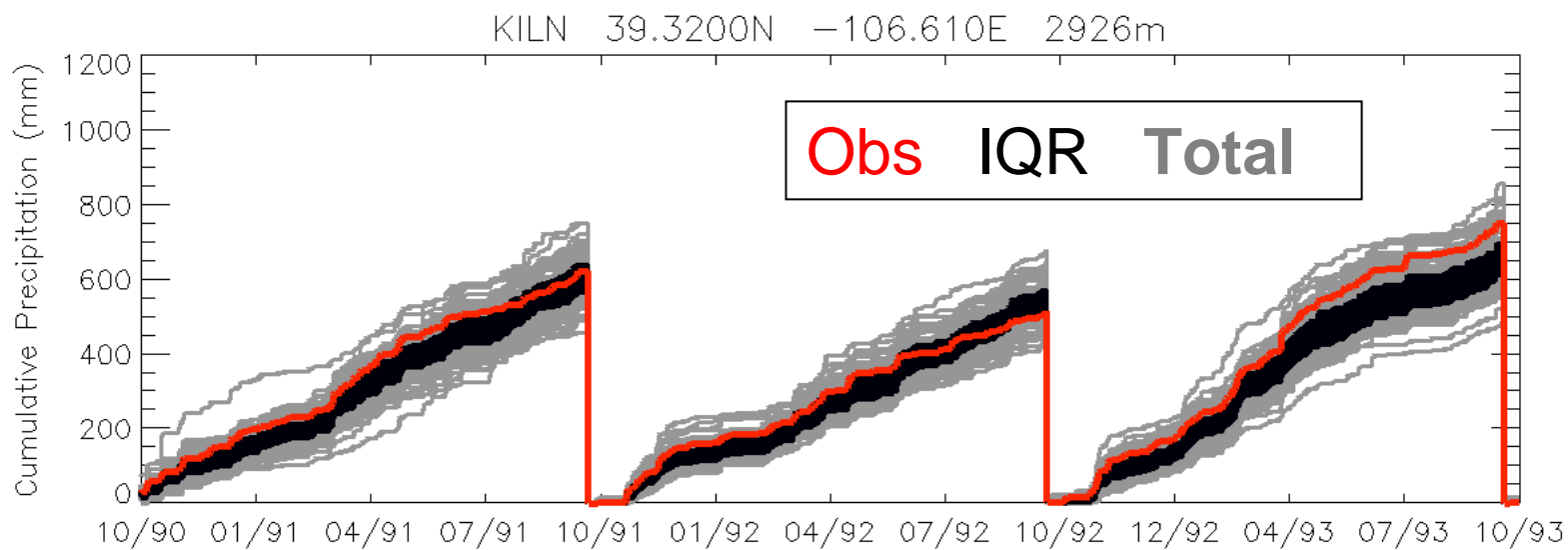
53 Upper C.R.B. SNOTEL Stations



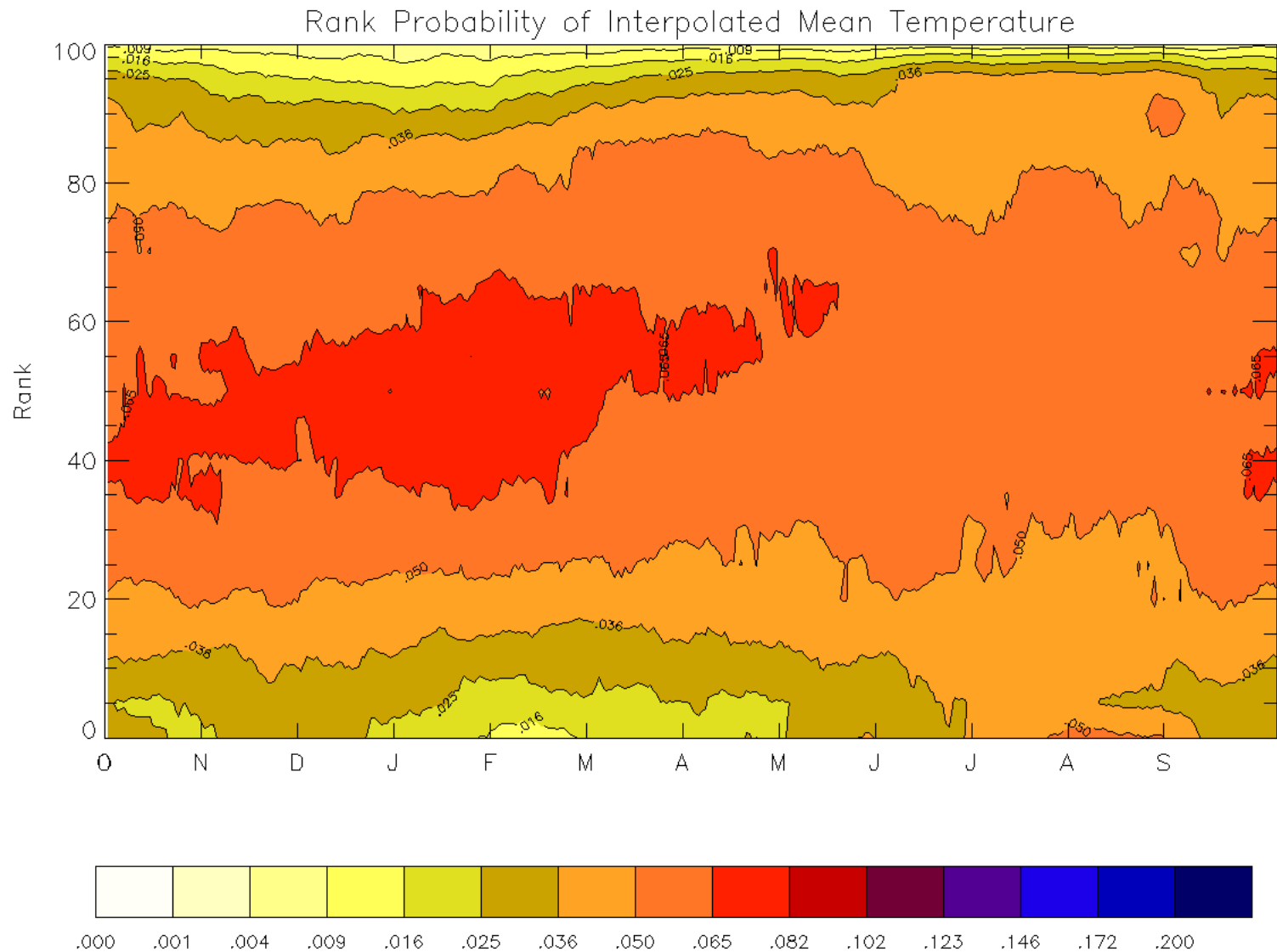
Example: Lake Eldora (forcing)



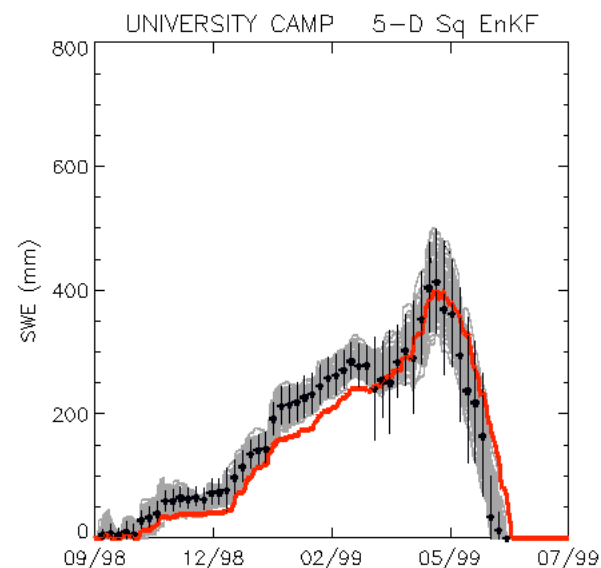
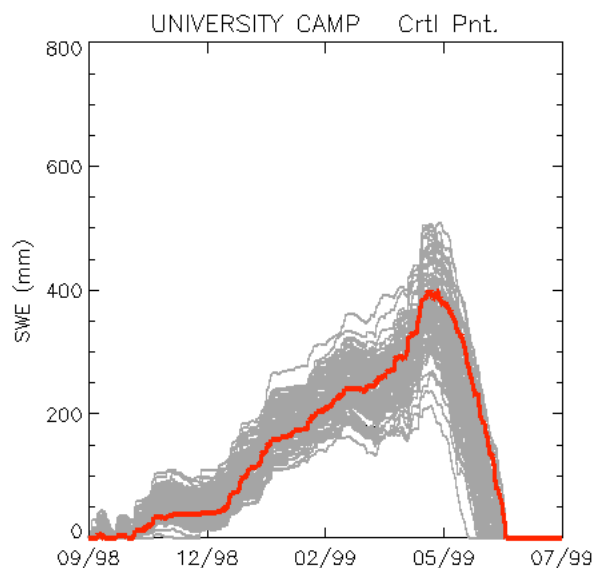
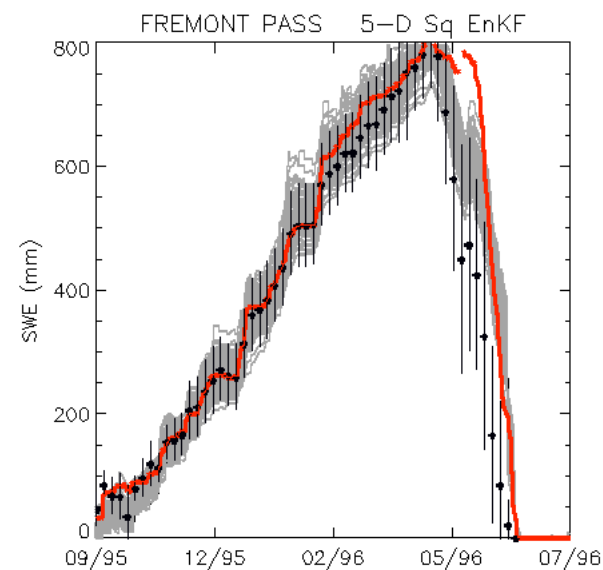
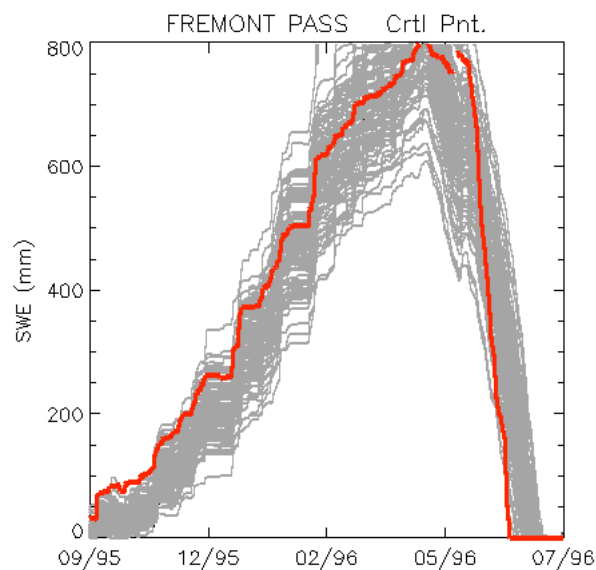
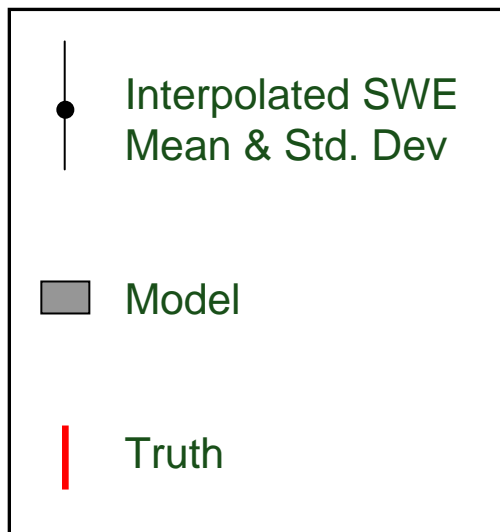
Example: Kiln (forcing)



Rank Probability of Temperature (All Stations)

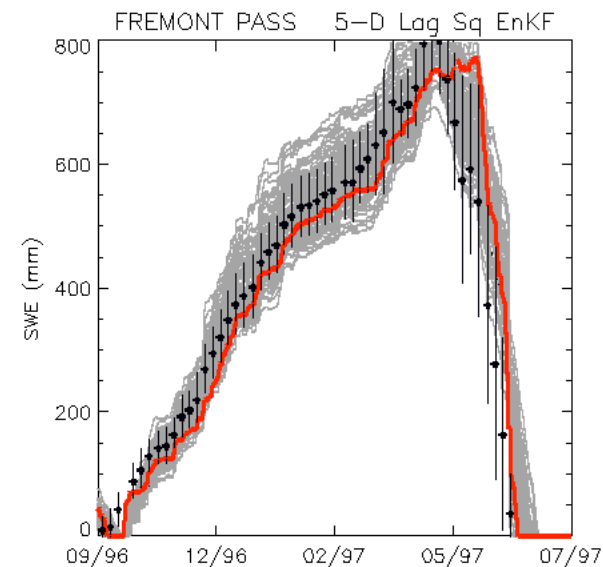
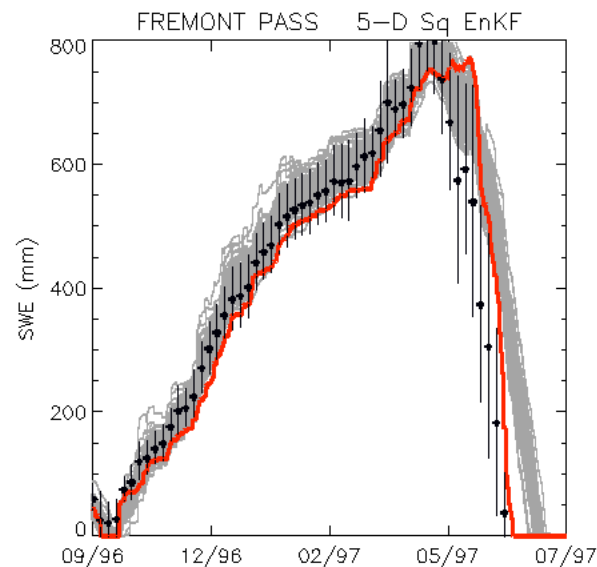
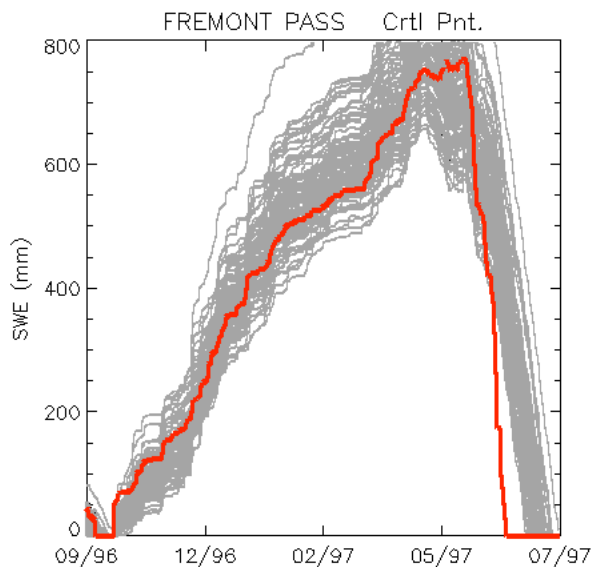


EnKF Sample Results

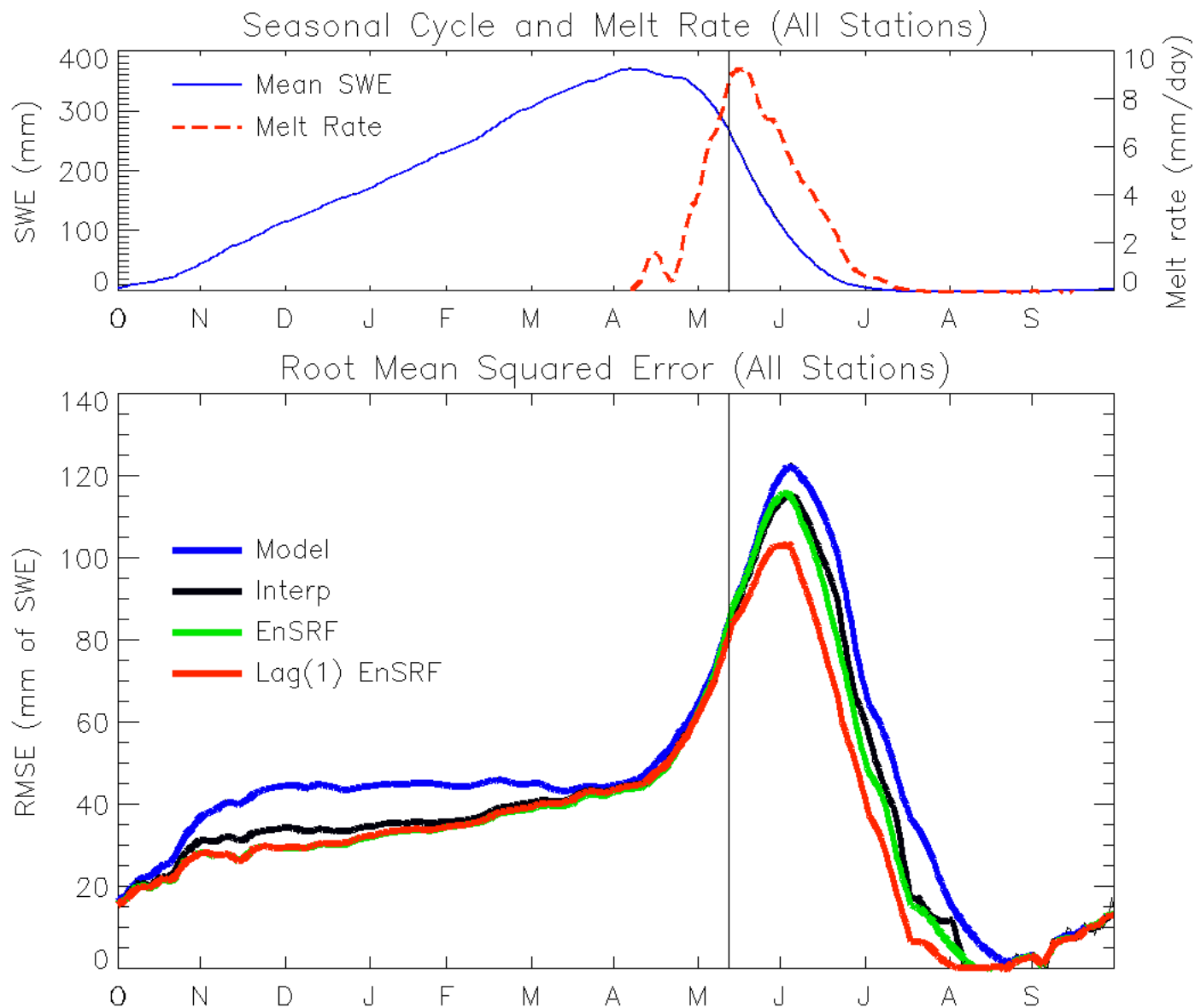


White without Red = B.L.U.E

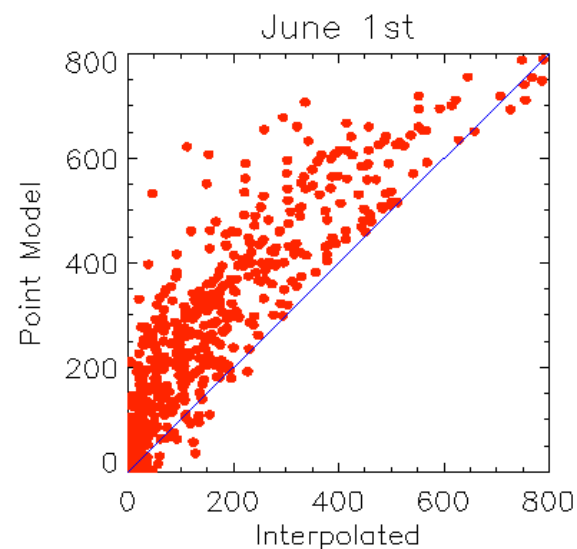
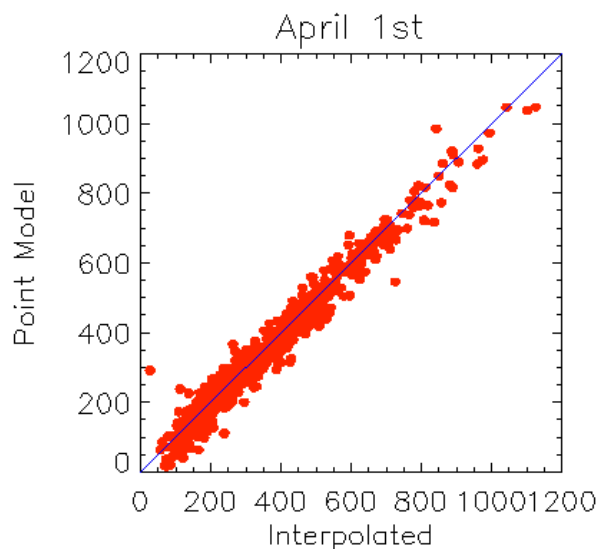
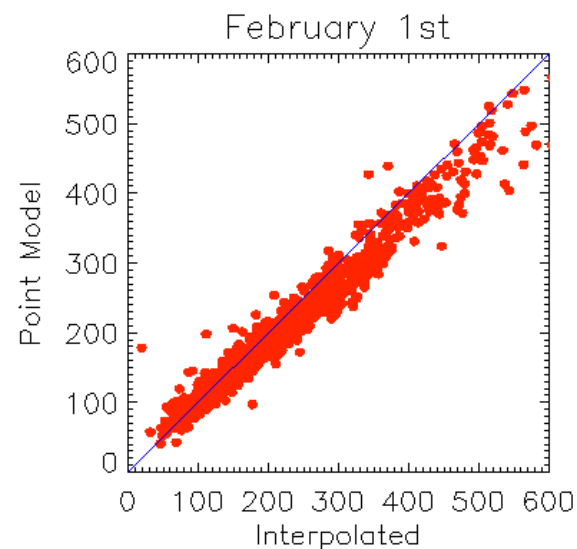
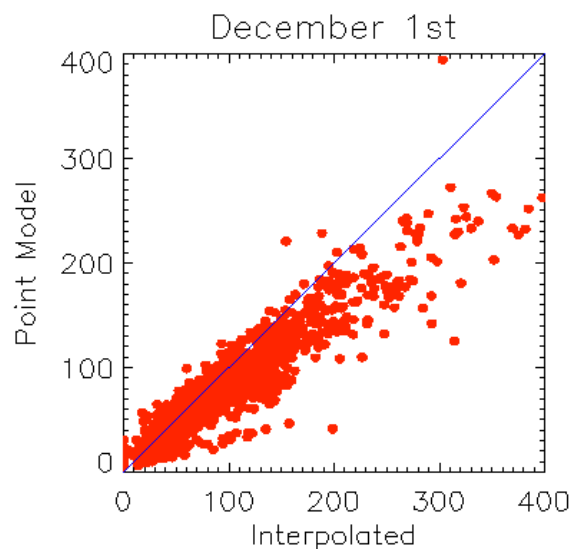
- SWE contains red (time correlated) noise
- Only want to use “new” information
- Example – assimilate at same timestep
- Filter Divergence = potential problem



Final Assimilation Results



Requirement : new & better information



Conclusions – Snow Data Assimilation

- Analysis superior to Model or Observations
- Correlation structure removed
- Only *one* area of uncertainty covered so far
- Limited data sources, so far
- Model *rebalanced* for forecasting
- Improves short term forecasting
- Operational capabilities!



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The End

Thank You