

Improvements of stream-flow predictions and flood forecasts

1. Error correction based on

- Wavelet transformations of observed and simulated discharge series to capture errors caused by different time scales, resolutions
- Vector AutoRegressive model with eXogenous Input (VARX) applied in the Wavelet domain (for each scale)

2. Predictive uncertainty estimation

- Bayesian Uncertainty Processor of the forecast (Krzysztofowicz, 1999)

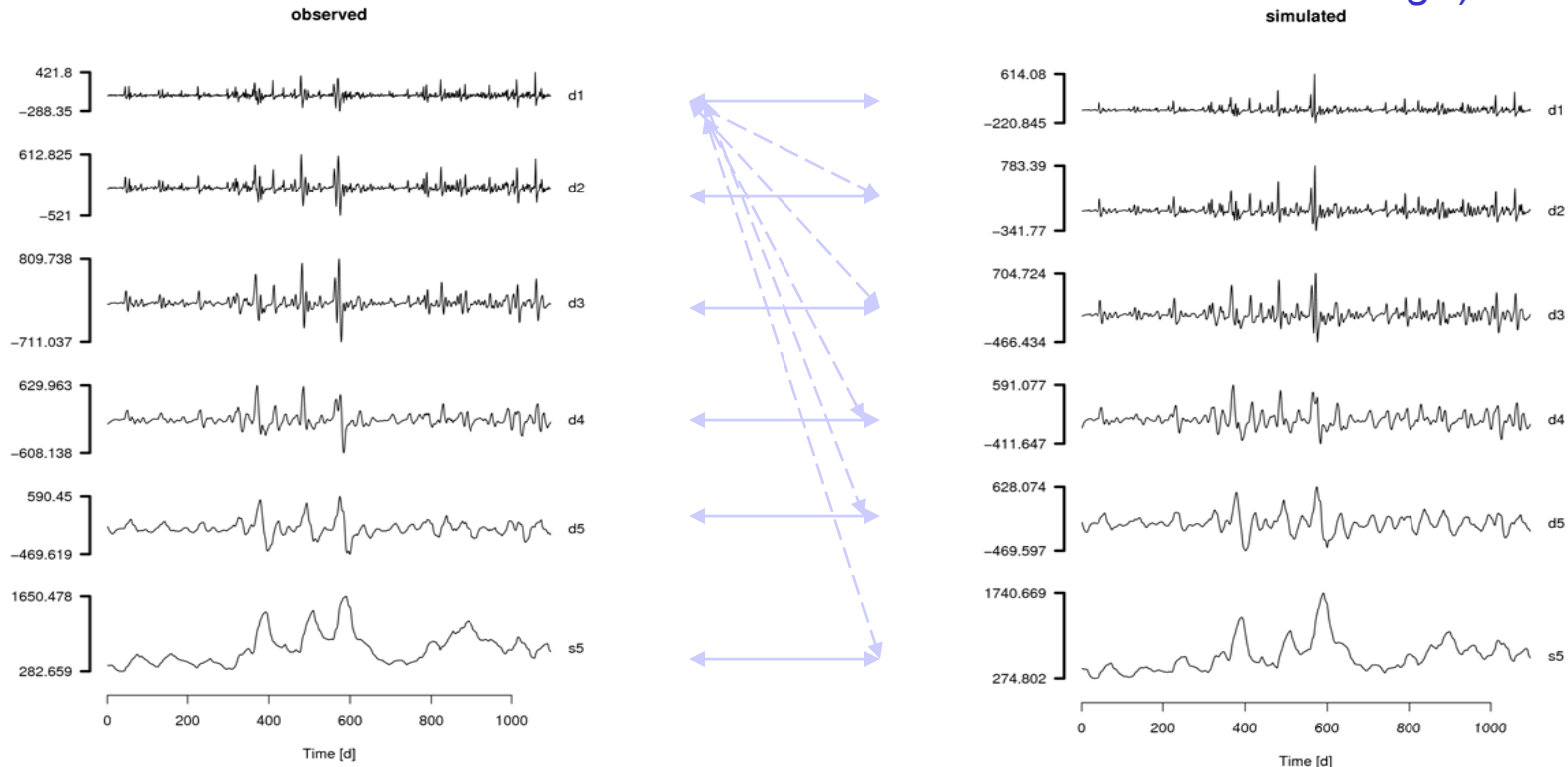
3. Forecast combination

- Deriving optimal weights (e.g. Bayesian Model Averaging)

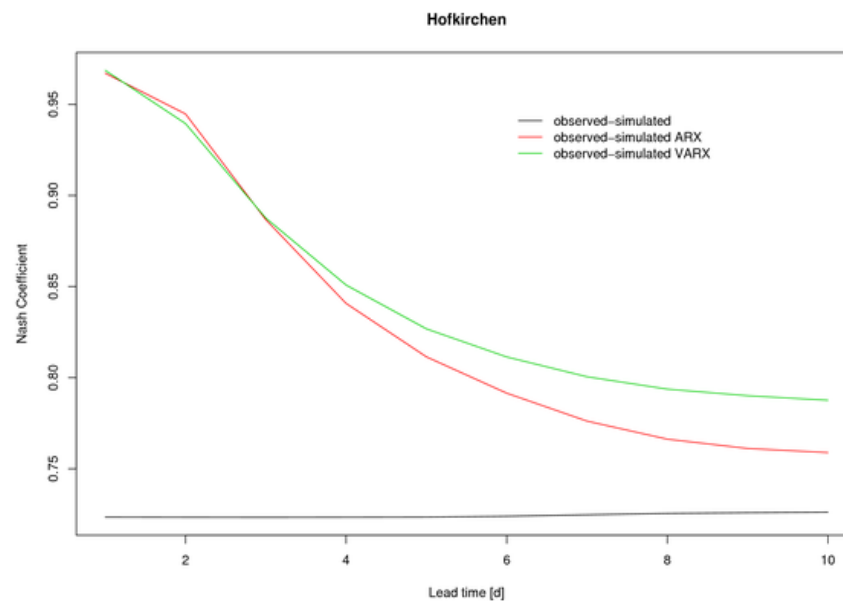
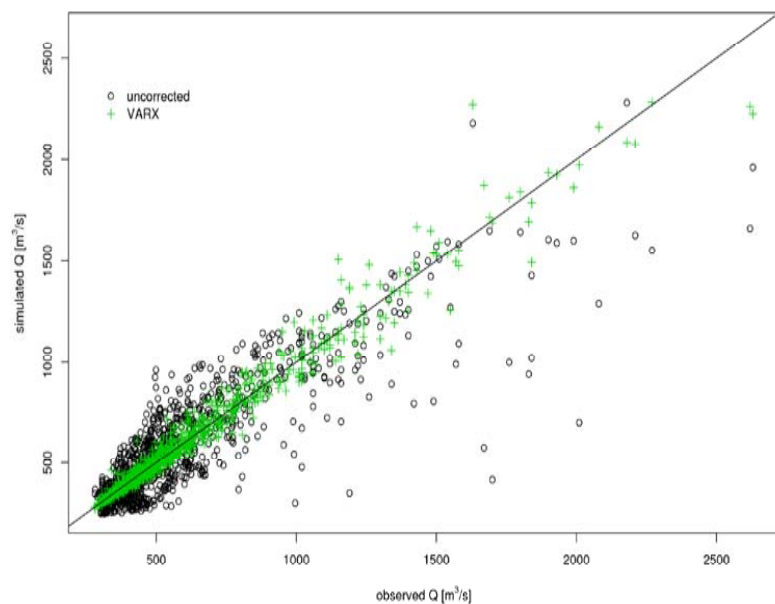
Predictand
(observed discharge)

1.1 Wavelet transformation

Predictor
(simulated/forecasted
discharge)



1.2. Fitting a Vector AutoRegressive model VARX in the Wavelet domain
(all levels of decomposition / resolutions simultaneously)

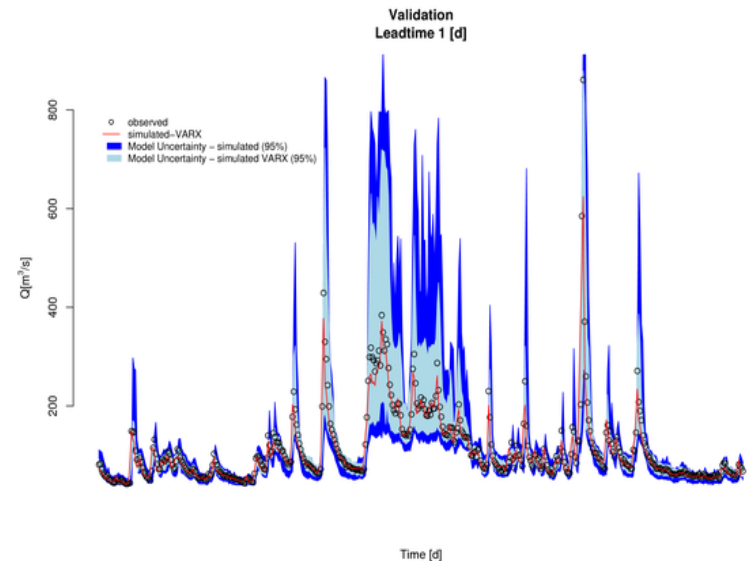
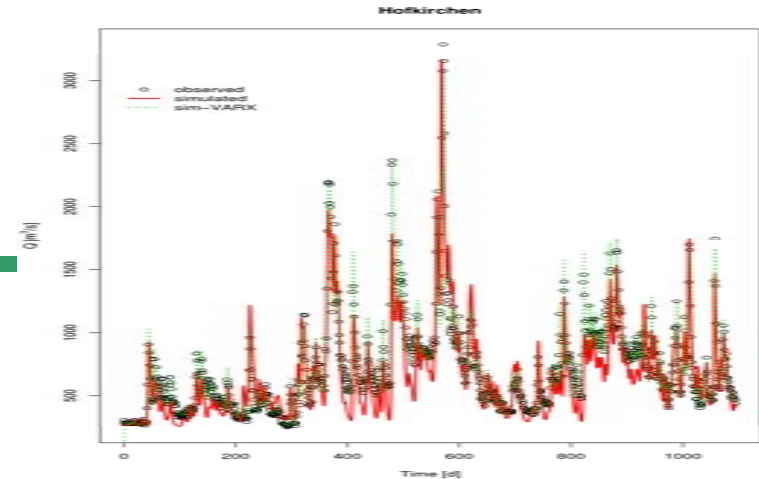


Normal quantile transform of
the observed and simulated
data

VARX predictions in the
wavelet domain

Deriving Uncertainties for
each lead time
(Krzysztofowicz, R.,
1999)

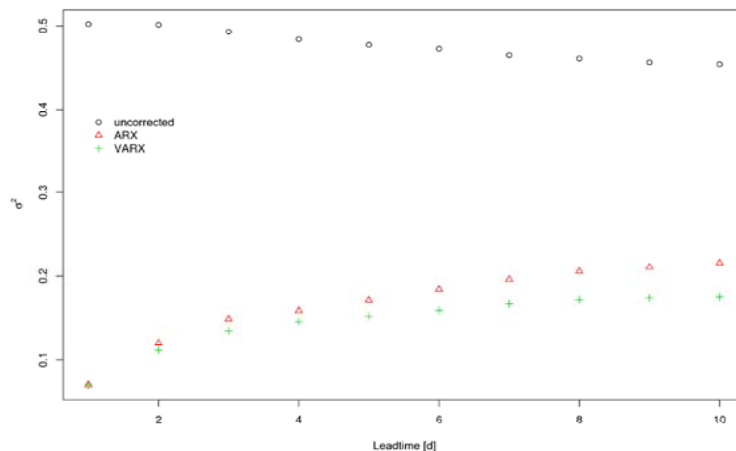
Back-transformation from
Gaussian space



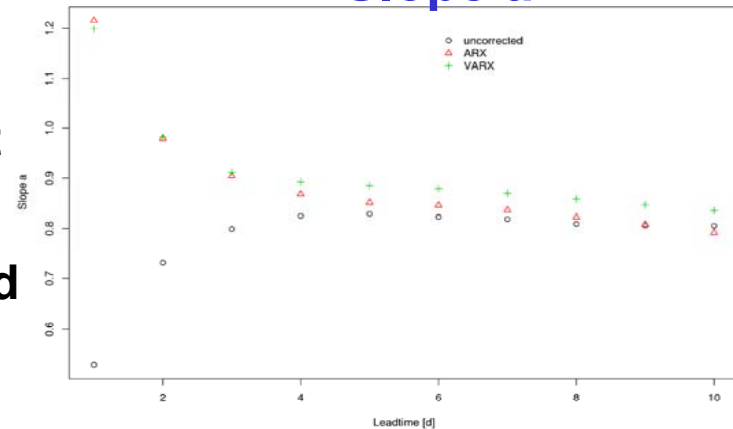
- **Slope a** measures how much information is in the output
- **σ^2** measures the "noise" of the output
- **Informativeness Score (IS,** (Krzysztofowicz (1992)) and is bounded between 0 (=uninformative predictor) and 1 (=perfect predictor)

$$IS = \left[\left(\frac{a}{\sigma} \right)^{-2} + 1 \right]^{-\frac{1}{2}}$$

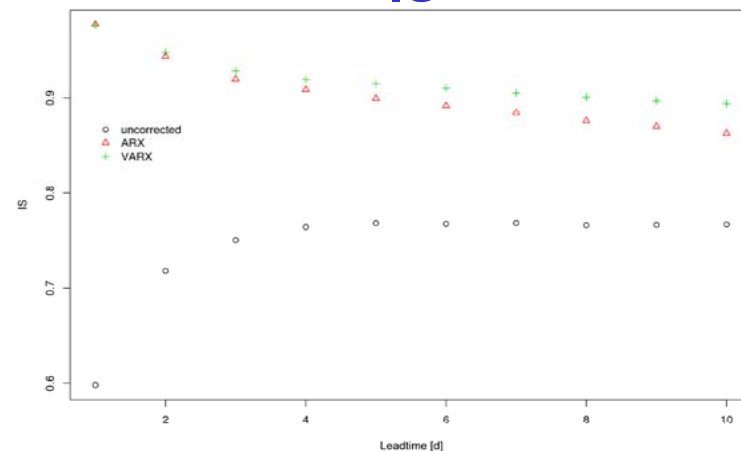
σ^2

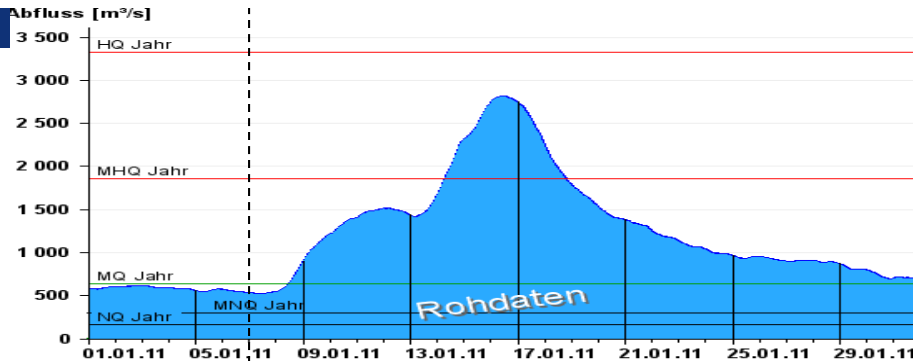


Slope a



IS





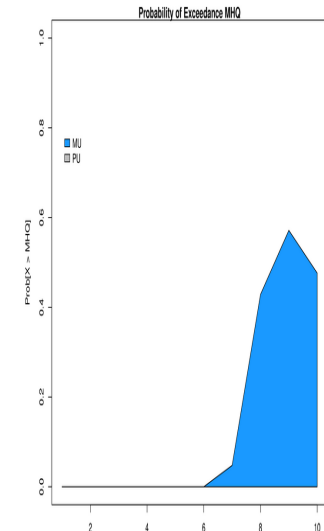
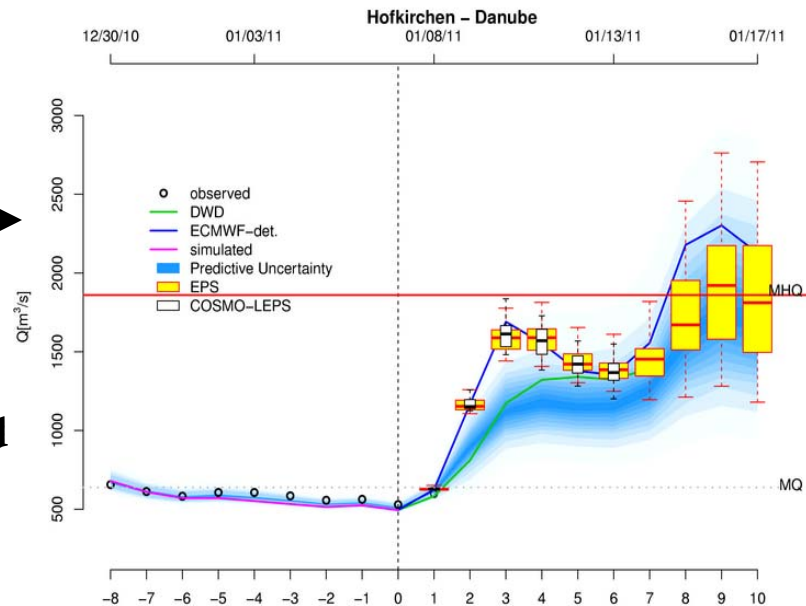
© Bayer. Landesamt für Umwelt im Geschäftsbereich des Bayer.
Staatsministeriums für Umwelt und Gesundheit

Measurements:

← Observed discharge time series at station Hofkirchen (Danube, Germany)

EFAS discharge forecast (based on meteorological forecasts initiated at 01/07/2011 12:00

(9 days before the flood peak)



Exceedance probability of the mean annual flood discharge (MHQ) vs. leadtime

Hydrological Uncertainty

Input Uncertainty

Integrator (HU + IU)

At the moment the Input Uncertainty is simply estimated by giving each of the deterministic forecasts (DWD + ECMWF) 25% and each EPS member 1% -> ~100%: “**empirical combination**”

Possible improvements: Combining forecasts giving different weights according to the forecast quality in the previous days

- **Heteroscedastic Normal Regression or Nonhomogeneous Gaussian Regression (EnsembleMOS, Gneiting et al. 2005)**

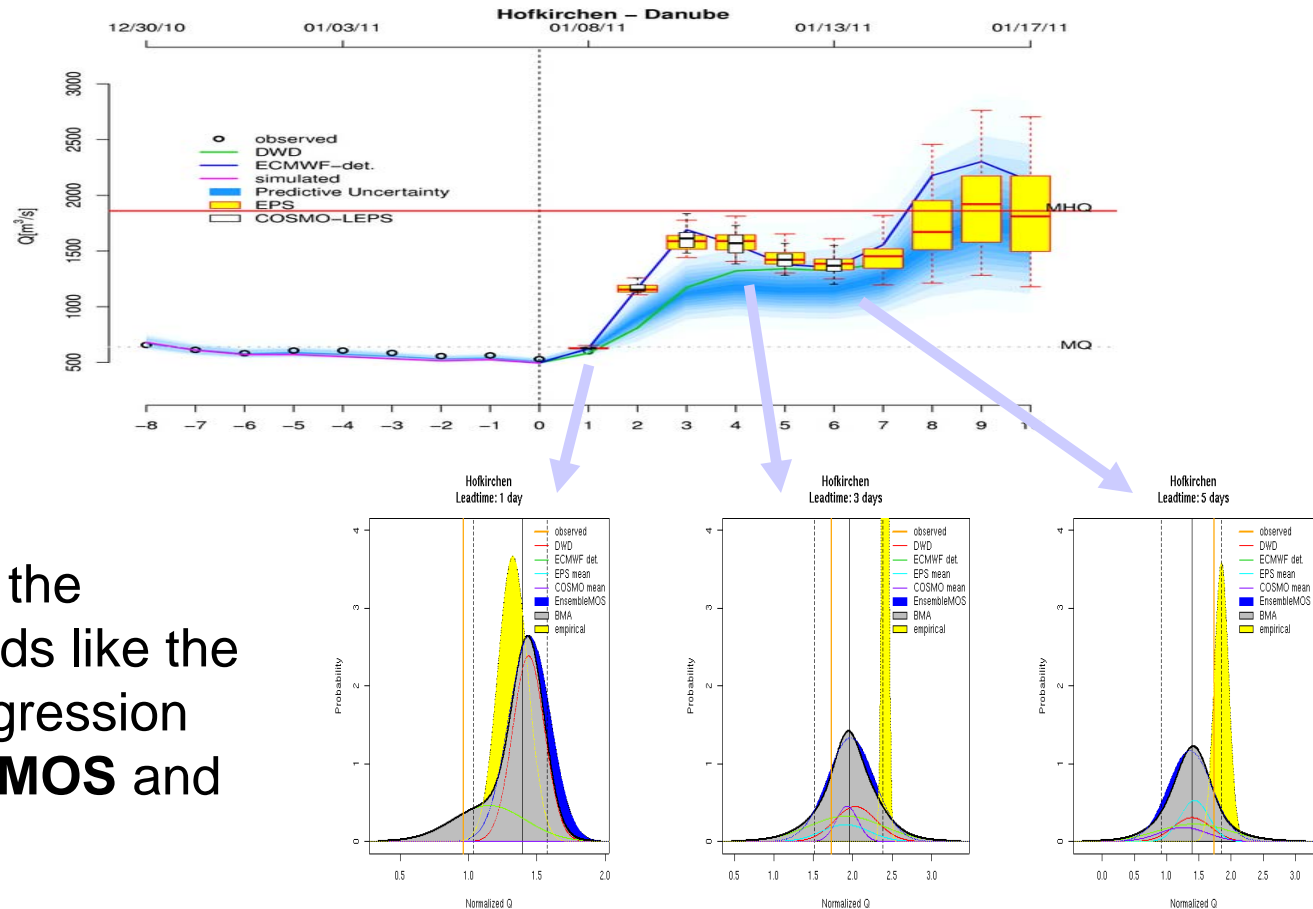
$$E(X_n | u, v) = v_n,$$

$$\text{Var}(X_n | u, v) = \tau_n^2$$

$$V_n = \beta_0 + \beta_1 X_{Det.DWD} + \beta_2 X_{Det.ECMWF} + \beta_3 \overline{X_{EPS}} + \beta_4 \overline{X_{LEPS}}$$

$$\tau_n^2 = g + hV_n$$

- **Bayesian model averaging**
 - **Dynamical updates -> quite intense in computing time**
- **Empirical method**



Some examples of the investigated methods like the heteroscedastic regression model - **EnsembleMOS** and **BMA** method.

- + Improvements by re-weighting the various actual forecasts conditioning on their past forecast performance.
- + The combination by the use of static, empirical derived weights results many times in over- or underdispersive forecasts depending on the state of the stream-flow

References:

- R. Krzysztofowicz. Bayesian correlation score: A utilitarian measure of forecast skill. *Monthly Weather Review*, 120(1):208–219, 1992.
- R. Krzysztofowicz. Bayesian theory of probabilistic forecasting via deterministic hydrologic model. *Water Resources Research*, 35(9): 2739—2750, 1999.
- T. Gneiting, A.E. Raftery, A.H. Westveld III, and T. Goldman. Calibrated probabilistic forecasting using ensemble model output statistics and minimum CRPS estimation. *Monthly Weather Review*, 133(5):1098–1118, 2005.
- Bogner, K., and F. Pappenberger (2011),
Multiscale Error Analysis, Correction and Predictive Uncertainty
Estimation in a Flood Forecasting System,
Water Resour. Res., doi:10.1029/2010WR009137, in press.