

HEPEX

a community of research and practice to advance
hydrologic ensemble prediction

Ensemble for Better Hydrological Forecasts
June 6-8, 2016

**Accounting for Combined Effects of Initial Condition and Model
Uncertainty in Seasonal Forecasting Through Data Assimilation**

Hamid Moradkhani

Contributors: H. Yan, M. Zarekarizi, C. DeChant

Civil and Environmental Engineering



Portland State
UNIVERSITY

1) Meteorological forcing

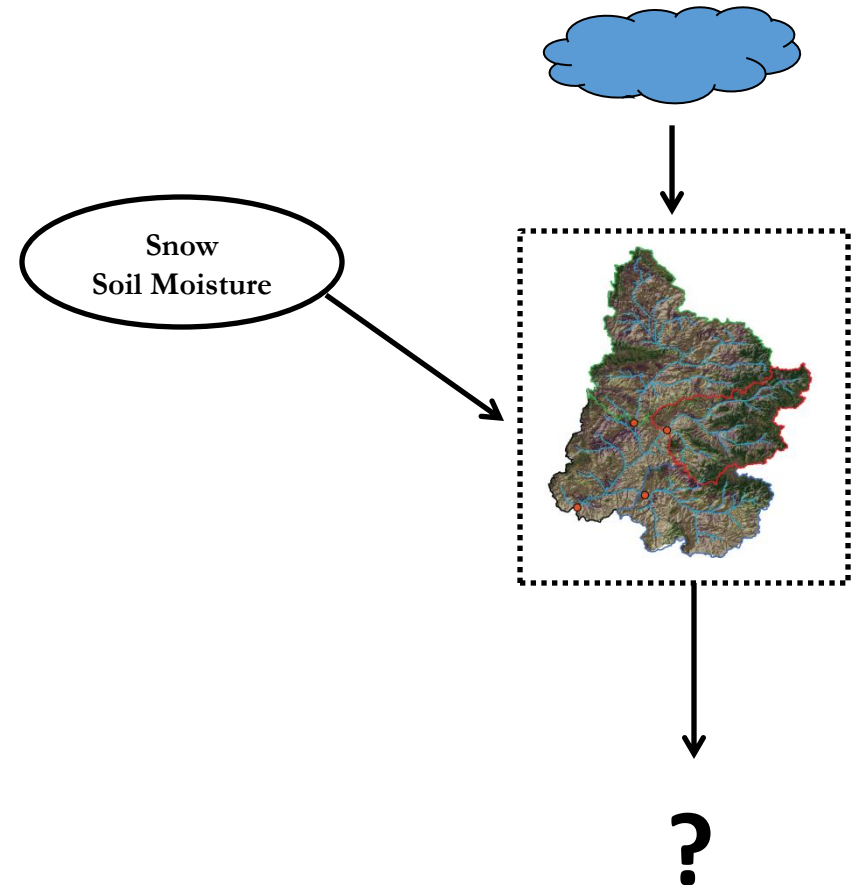
- Earth's chaotic atmosphere makes forecasting unreliable at extended lead times

2) Initial condition (states)

- Land surface hydrological conditions are highly variable spatially (e.g., snow and soil moisture)

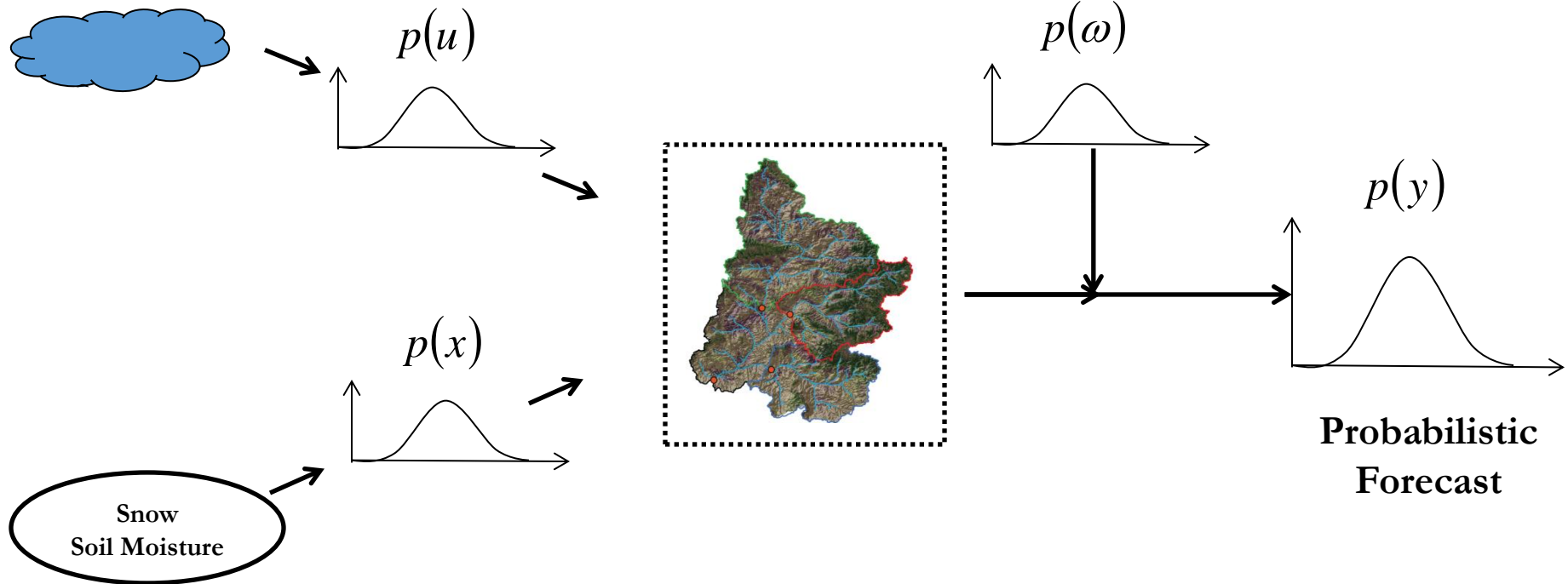
3) Hydrologic model

- Hydrologic models are simplifications to land surface processes



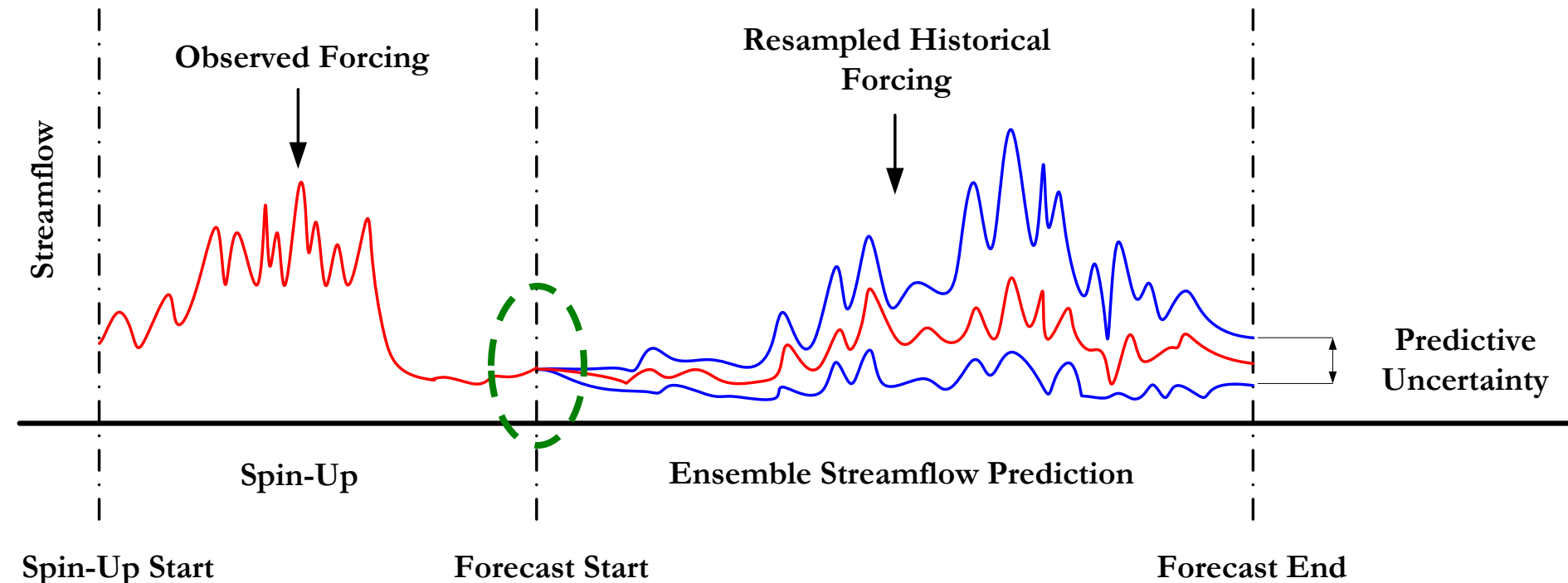
- Requires the formulation of a probabilistic model

$$p(y) = f(p(x), p(u), q) + p(w)$$



- Generated with Ensemble Streamflow Prediction (ESP)
- This ignores initial state and model uncertainty
 - **Ensemble Data Assimilation**

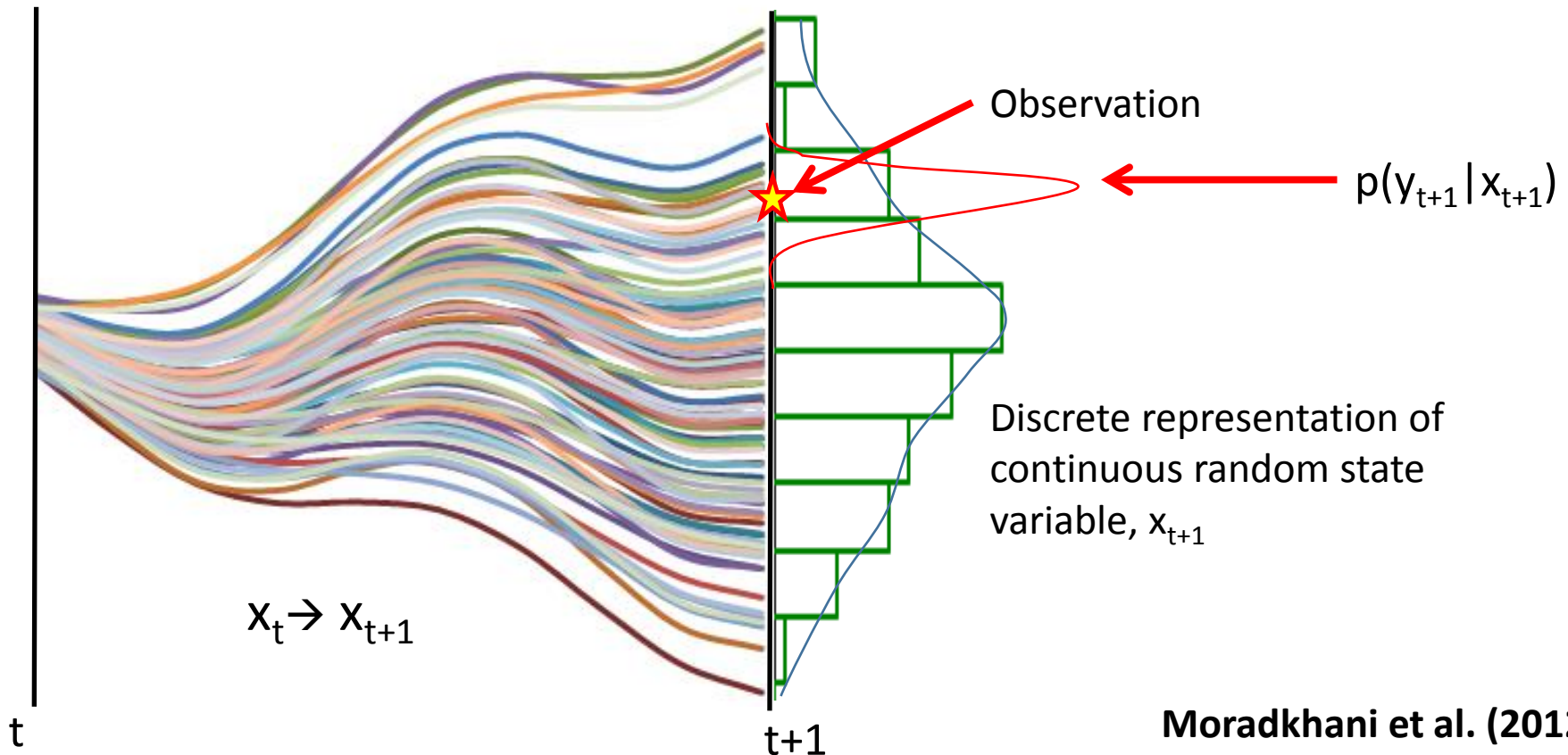
DeChant and Moradkhani (2011)



$$p(x_{t+1} | Y_{t+1}) = \frac{p(y_{t+1} | x_{t+1}) p(x_{t+1} | Y_t)}{\int_{x_{t+1}} p(y_{t+1} | x_{t+1}) p(x_{t+1} | Y_t) dx_{t+1}}$$

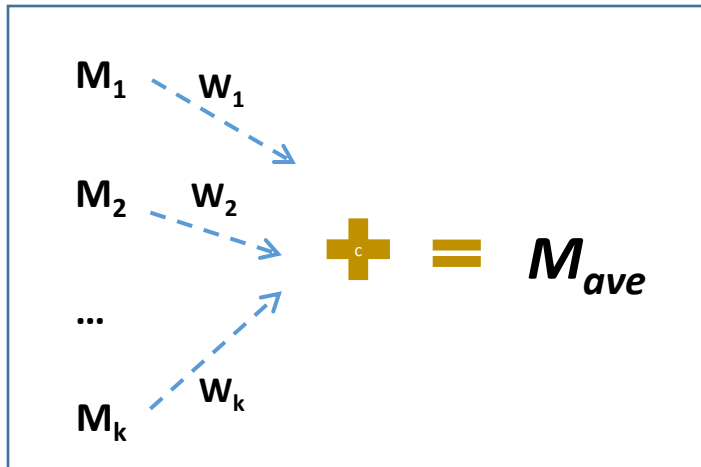
The Forecast (prior distribution)

$p(x_{t+1} | Y_t)$



MA is a linear weighted average of model ensembles.

Deterministic

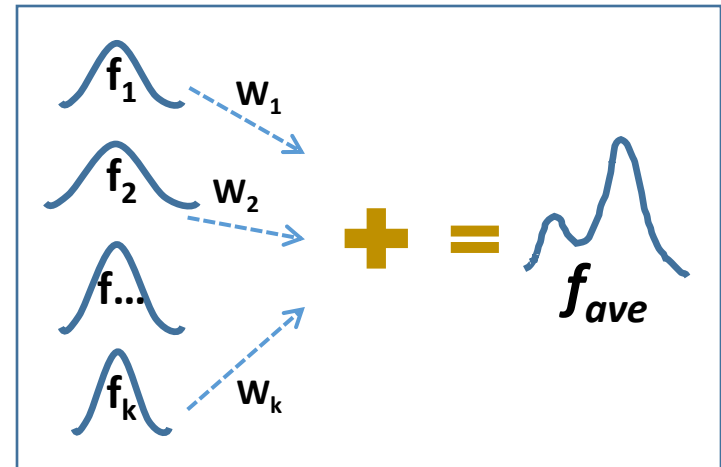


➤ Combines single-value forecasts.

$$M_{ave} = W_1 \cdot M_1 + W_2 \cdot M_2 + \dots + W_k \cdot M_k$$

- Examples: Equal weights, Bates-Granger averaging, AIC and BIC-based model averaging.

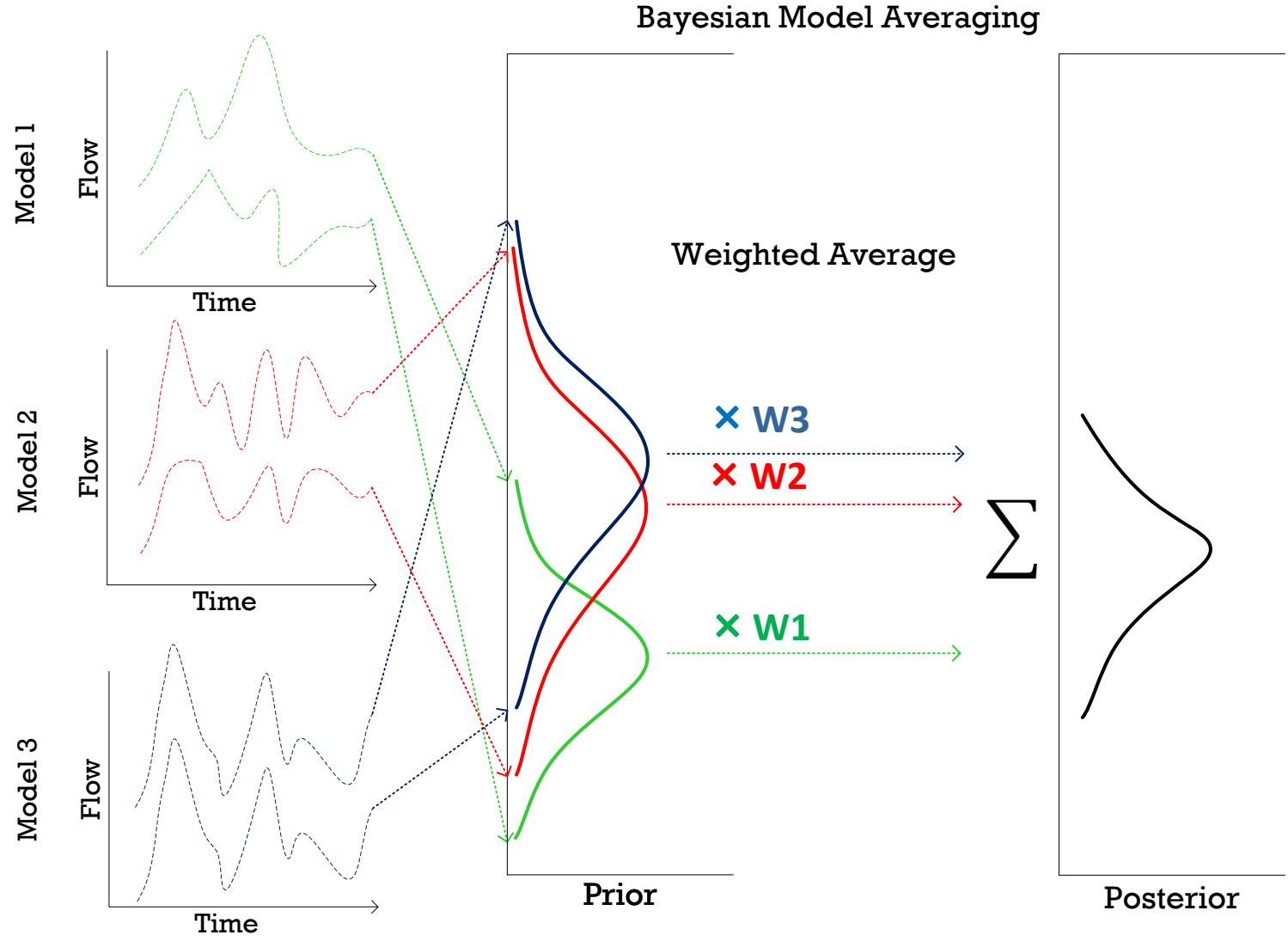
Probabilistic



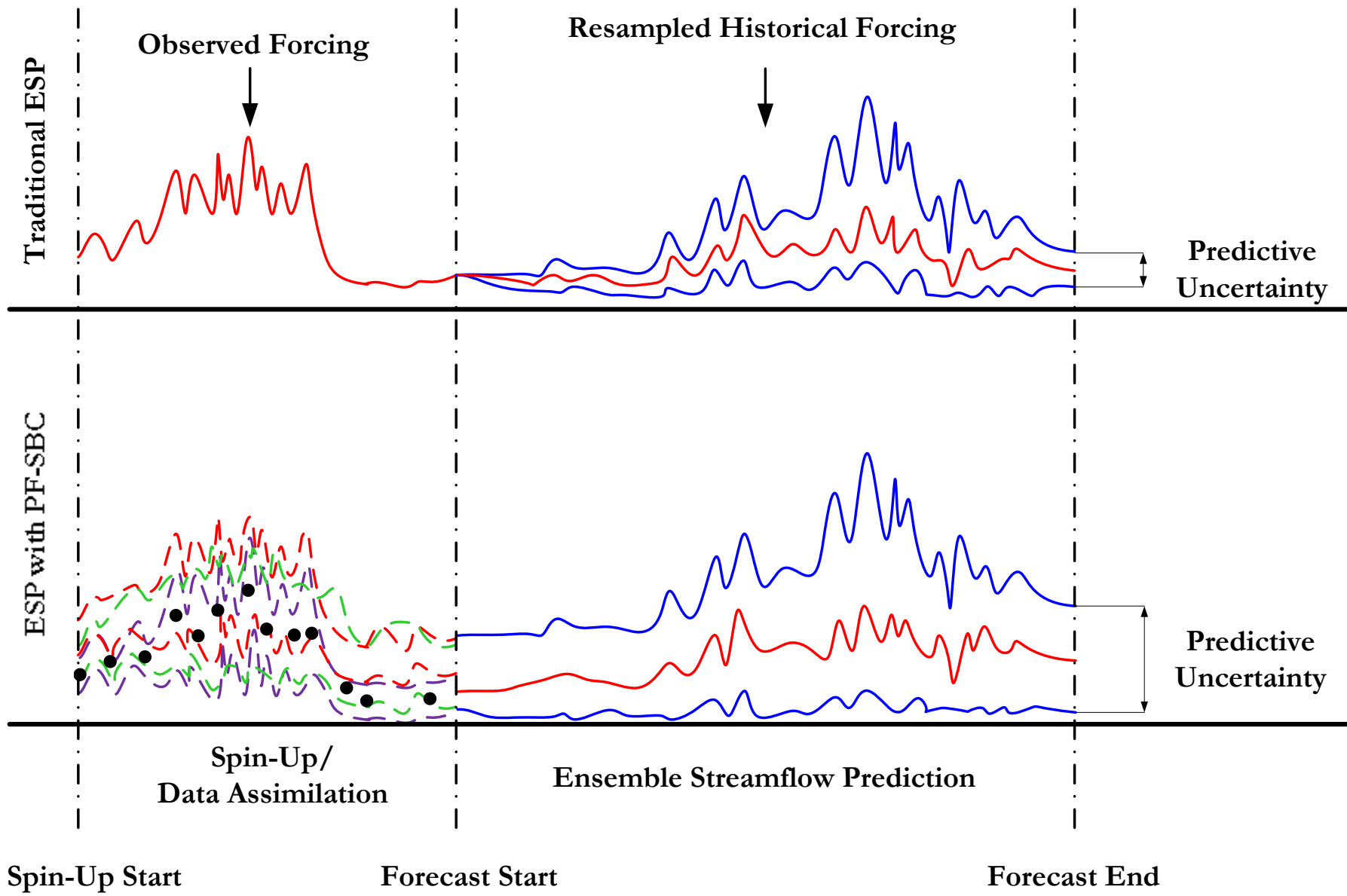
➤ Combines PDF of forecasts:

$$f_{ave} = W_1 \cdot f(M_1) + W_2 \cdot f(M_2) + \dots + W_k \cdot f(M_k)$$

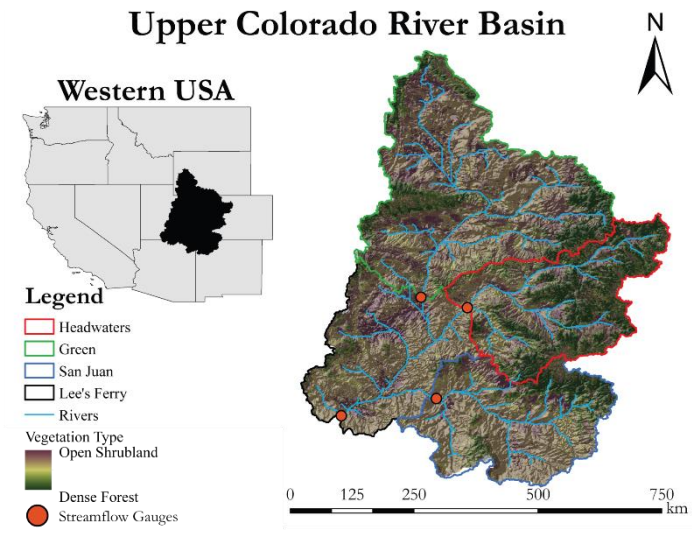
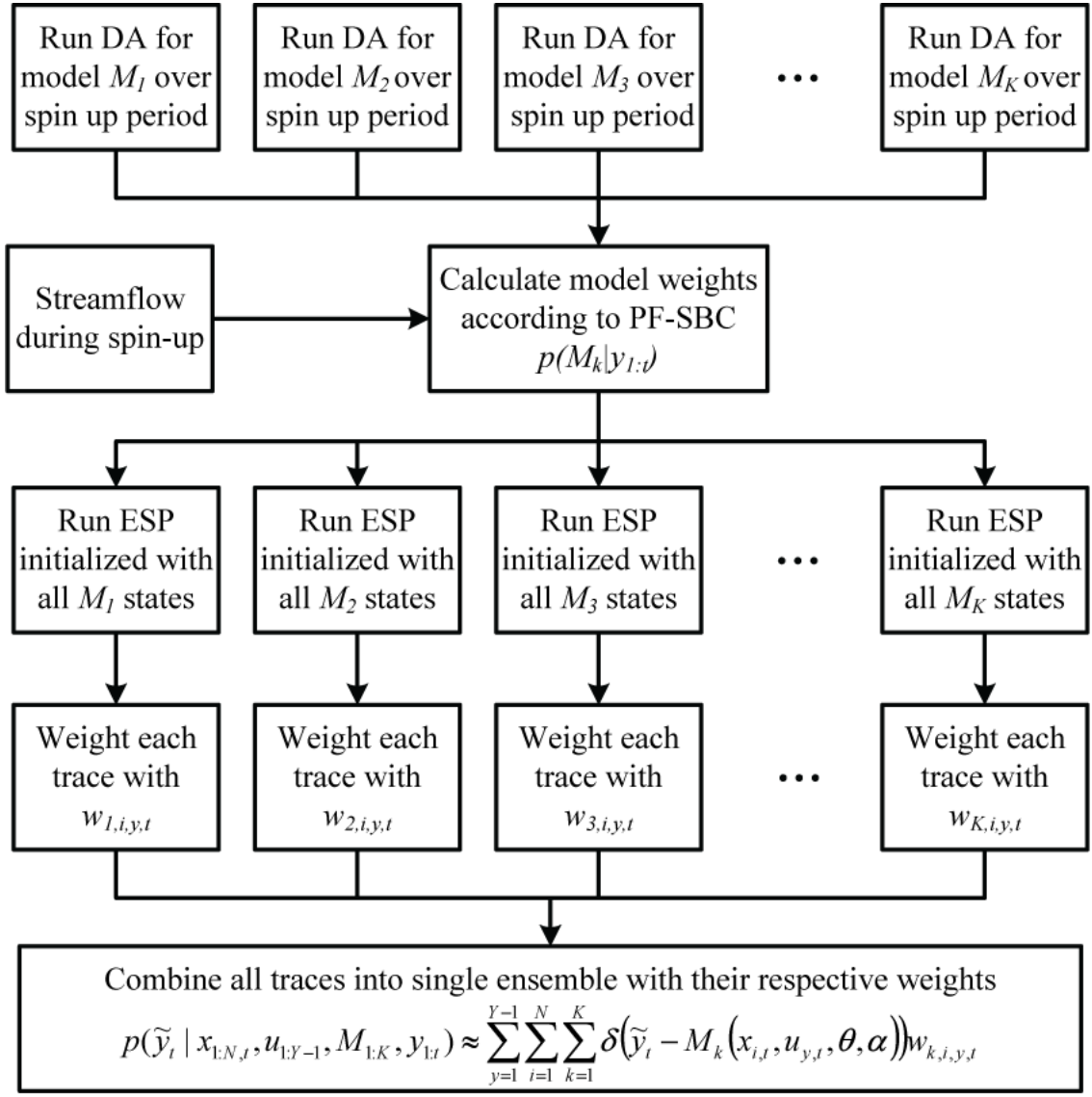
– Example: Bayesian Model Averaging



Combining PF-SBC with ESP



Combination of DA, Multi-modeling and ESP



- Two Models

- 1) Variable Infiltration Capacity (VIC)

- Physically-based distributed model

- 2) Coupled SNOW-17 and Sacramento models (NWS)

- Conceptual semi-distributed models

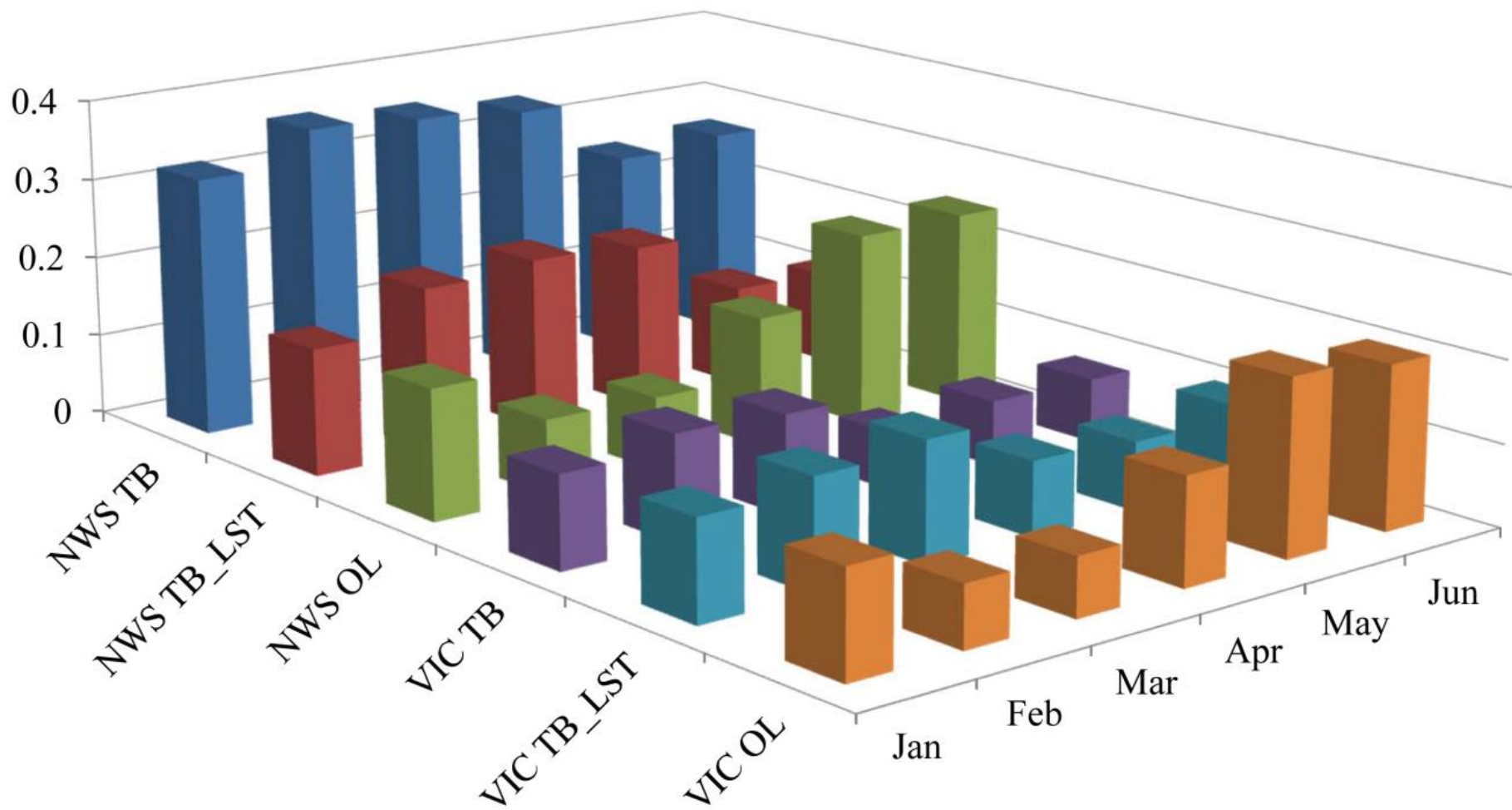
- Three cases for forecast spin-up

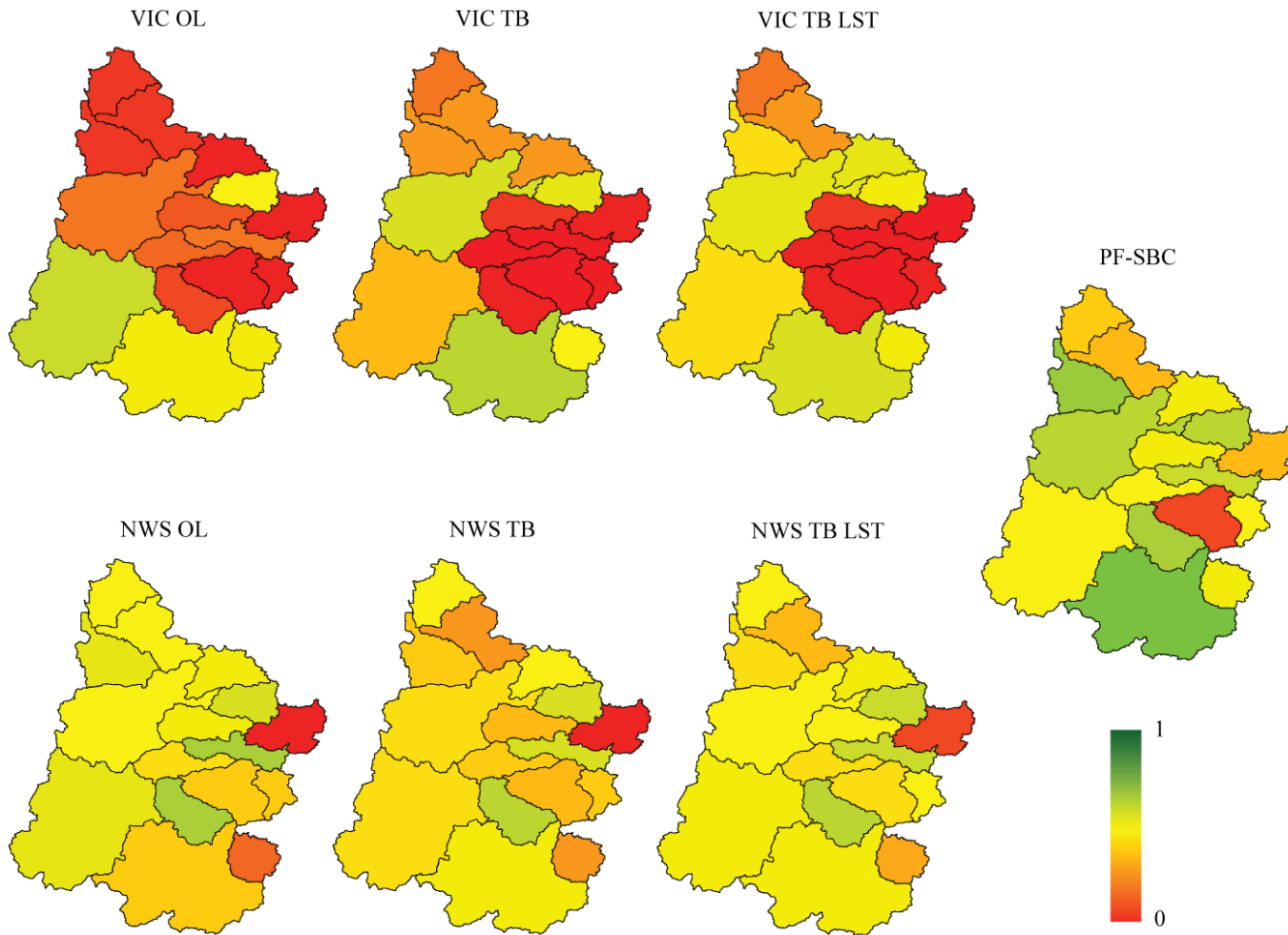
- 1) Open Loop (no assimilation)

- 2) Passive Microwave Brightness Temperature (TB)

- 3) Land Surface Temperature (LST) with TB

Weights or Importance of Each Model





Multi-remotely sensed Data Assimilation. PF-SBC is showing combined data assimilation and Multi-Modeling

Implement data assimilation within FEWS framework

- Build a system that allows for implementation with any model connected to FEWS (even models that will be connected in the future)
- Make the system flexible, allowing users to adjust the application of data assimilation (lumped vs distributed, multiple data sources, complex timing of observation time-series ...)
- Utilize existing FEWS-CHPS functionalities to simplify the data assimilation program

- The general FEWS workflow system is not conducive to DA
 - Entire time series are sent to models
 - Lots of I/O – computationally expensive
- Balance of computational demand, flexibility of framework and minimization of coding
 - Depending on where the DA algorithm is placed, the computational demand, model flexibility and amount of coding necessary will be effected
- Opted for significant coding in the pursuit of system flexibility with minimal computational cost
 - Required software development to create a data assimilation model driver (DADriver)

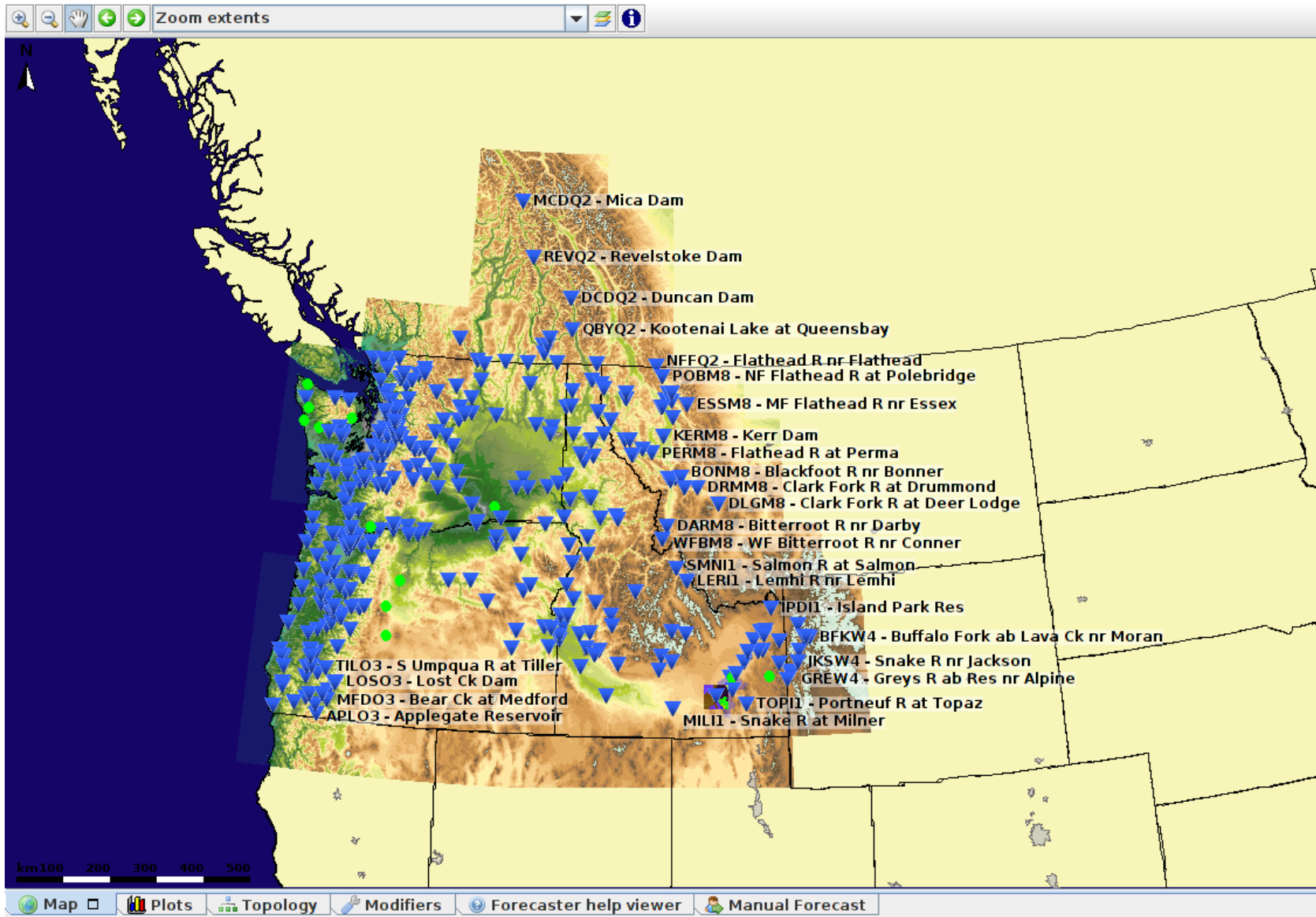
No Data Assimilation

- OHDFewsAdapter ships data for model runs one at a time
- Each model's driver performs simulation over the whole time series
- OHDFewsAdapter imports output data from single model

Data Assimilation

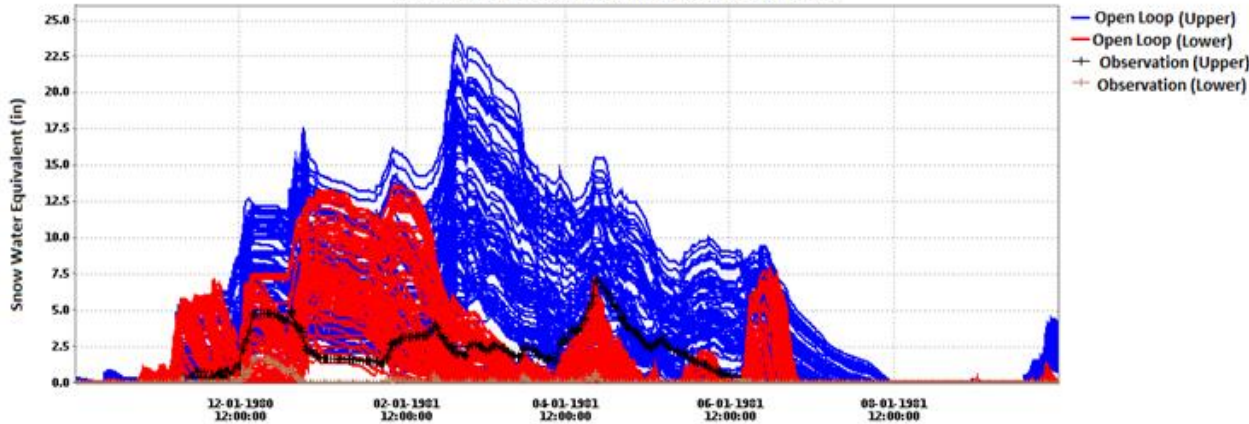
- OHDFewsAdapter ships data for multiple model runs
- DADriver only gives data required to run driver to the next observation
- OHDFewsAdapter imports data from all models involved in DA simultaneously

Data Assimilation within FEWS/CHPS Over the Pacific Northwest US

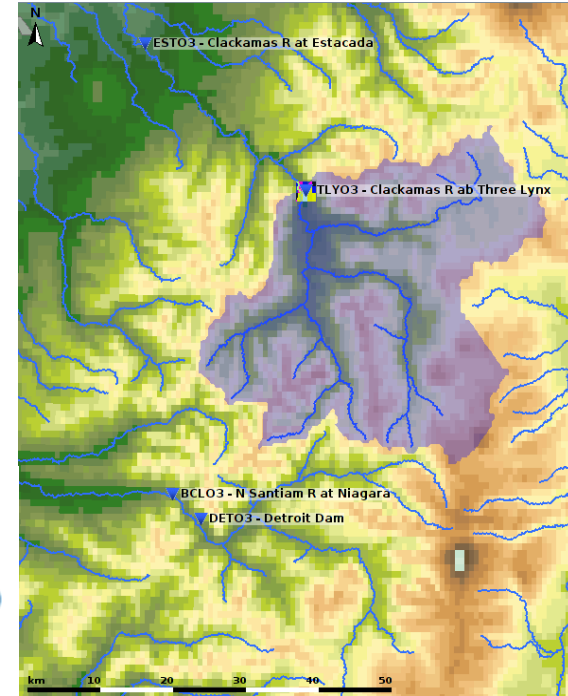
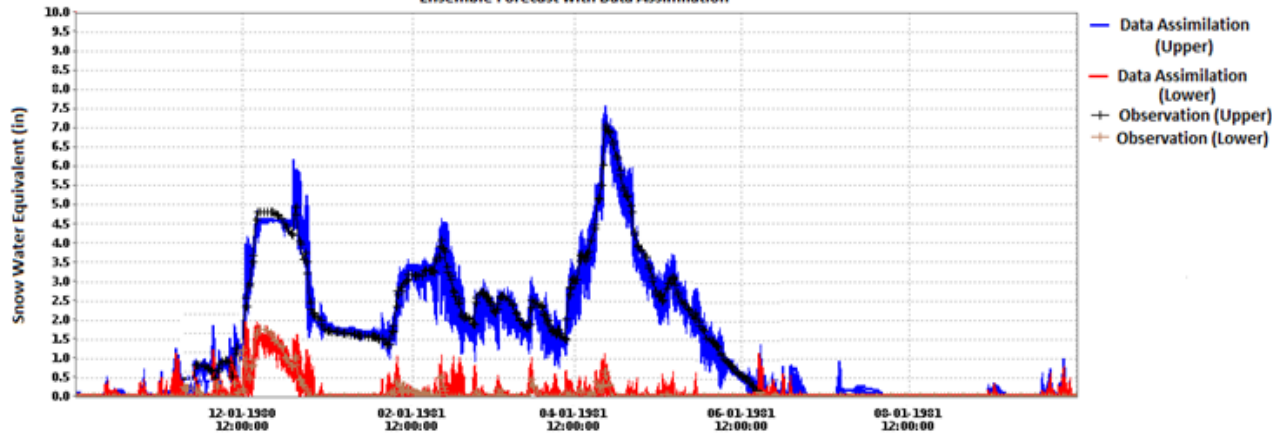


Ensemble Simulation for SWE before and after DA Clackamas River Basin

Ensemble Forecast - Open Loop (without Data Assimilation)

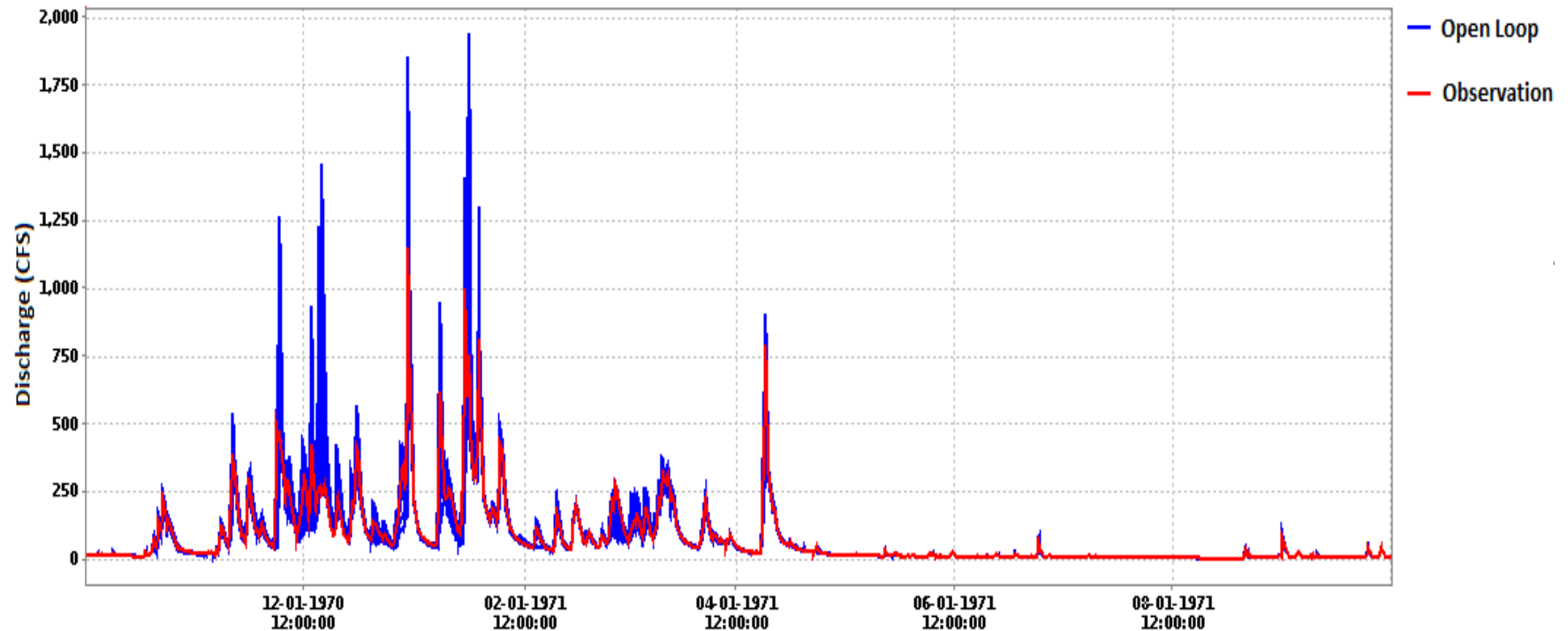


Ensemble Forecast with Data Assimilation

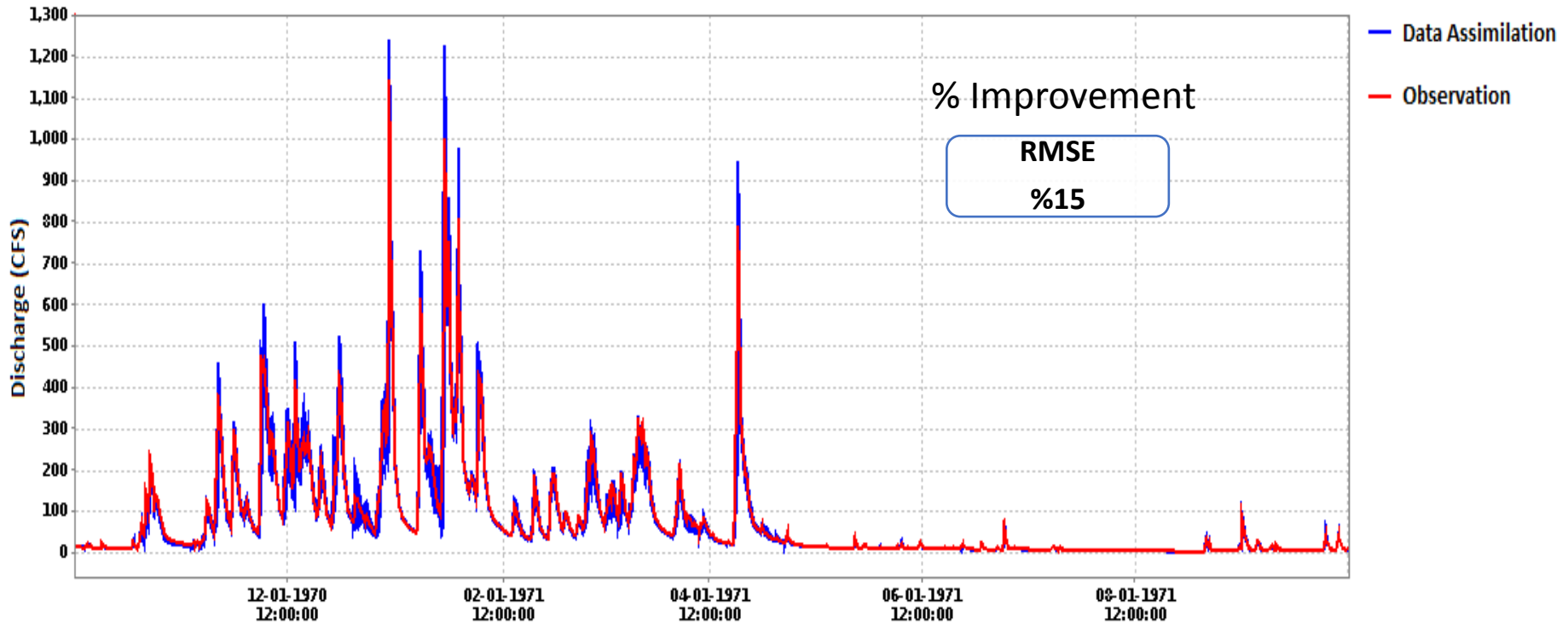


Before DA

Ensemble Forecast- Open Loop (without Data Assimilation)

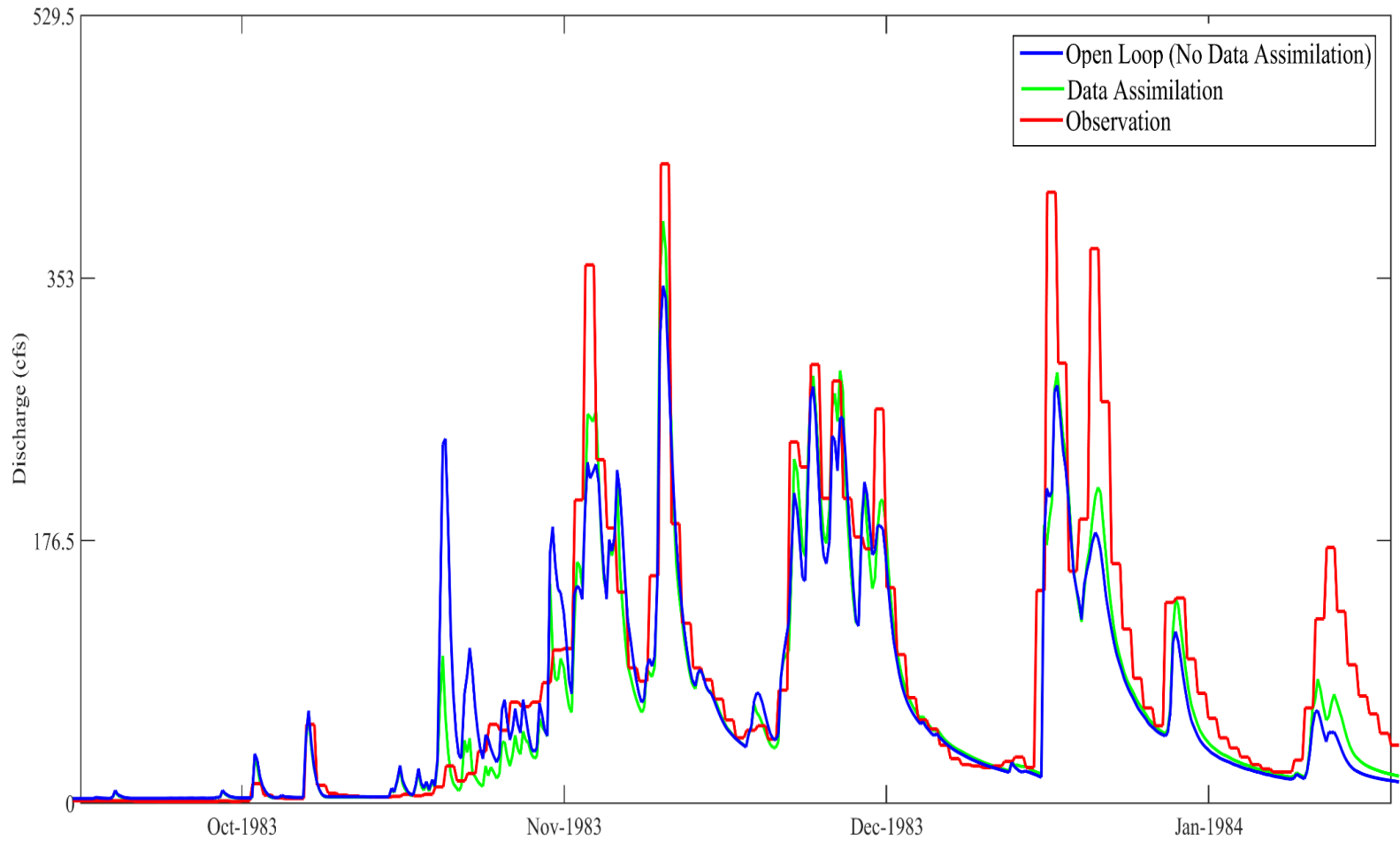


Ensemble Forecast with Data Assimilation



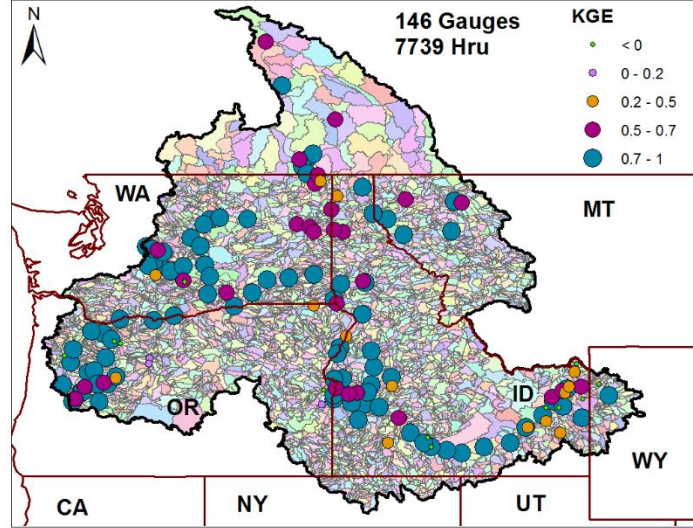
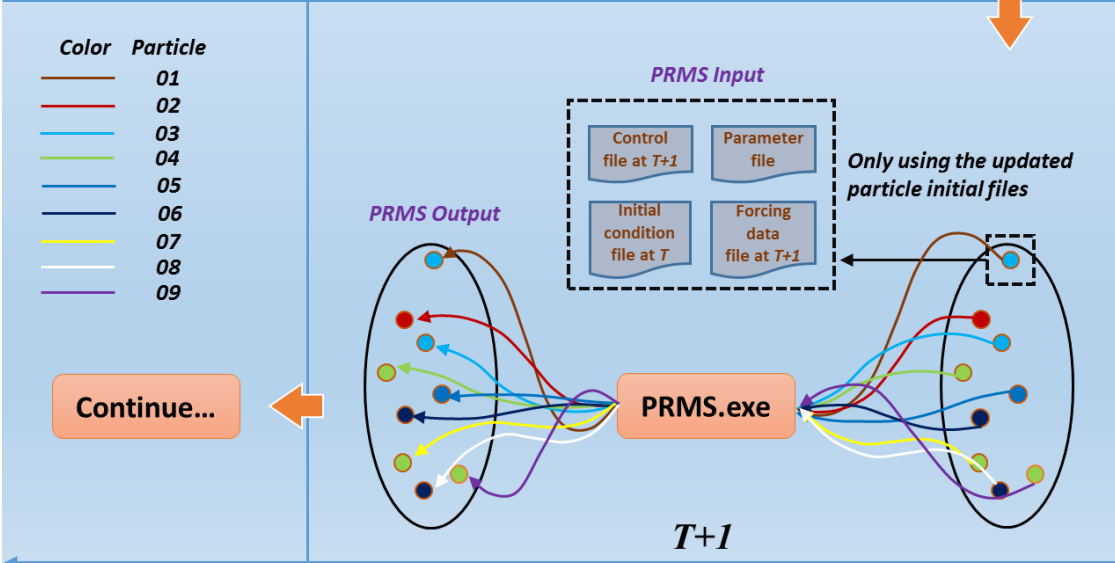
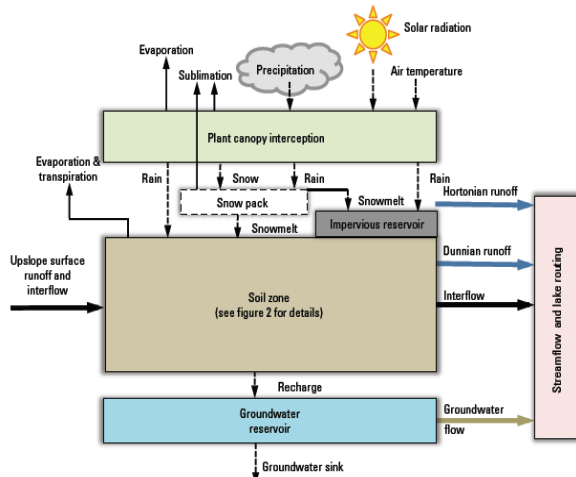
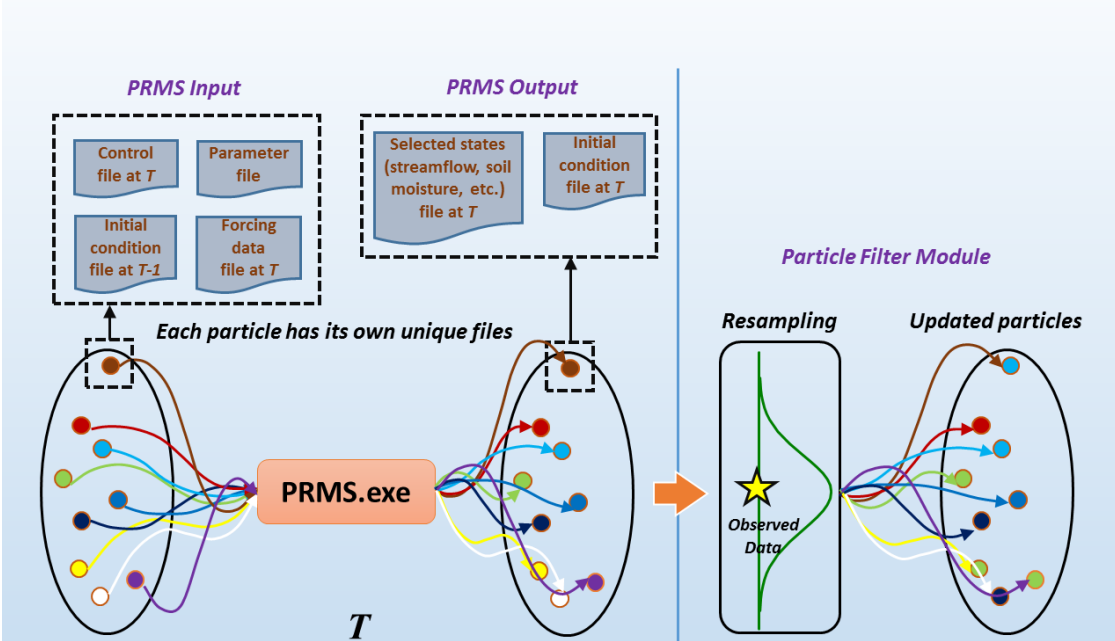
Streamflow Forecast before/after DA

“Johnson Creek”

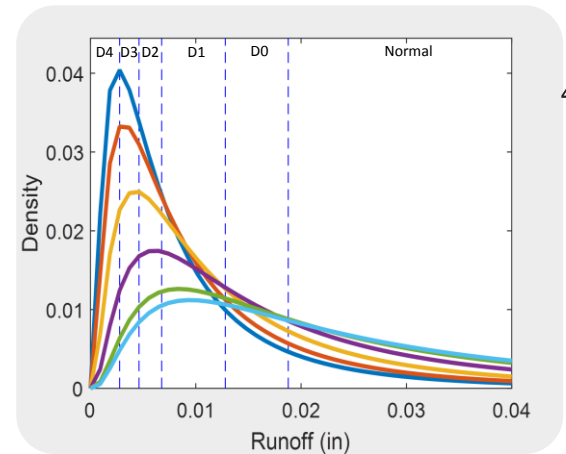
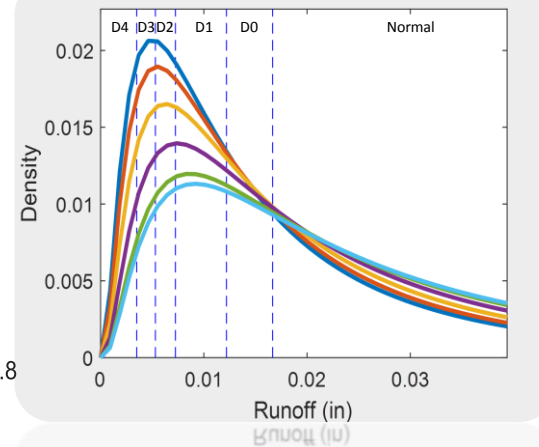
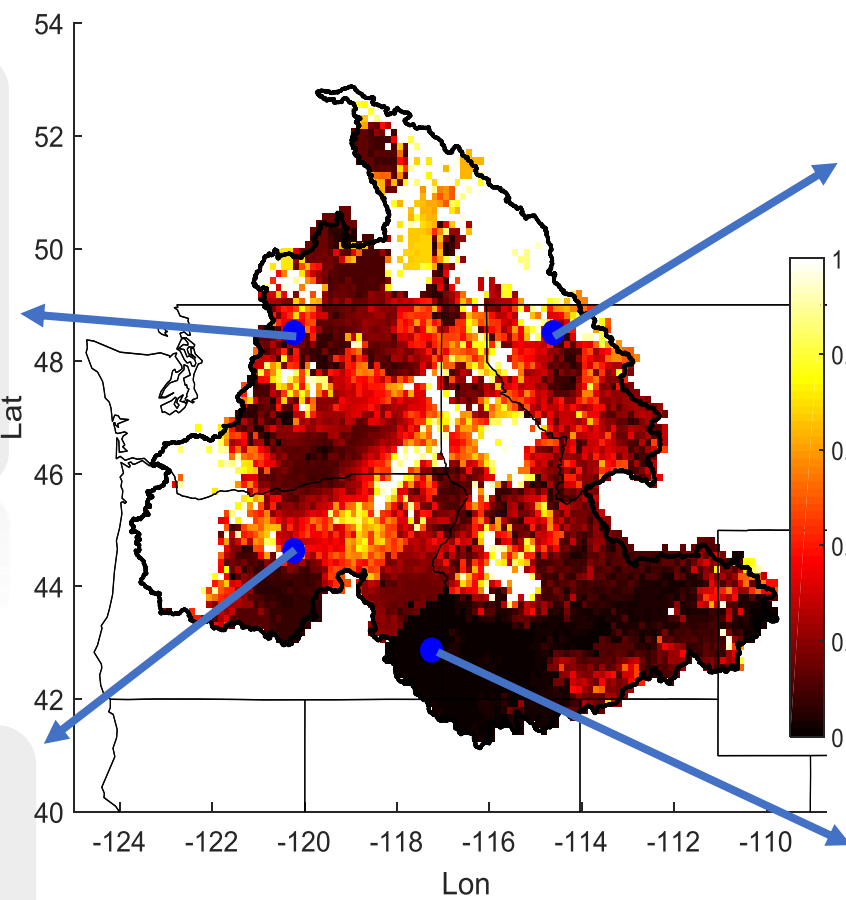
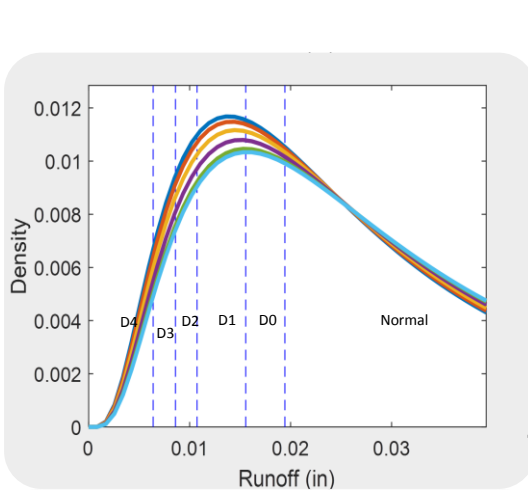


- The proposed method was verified with two drought events in 2013 and 2015 in Pacific Northwest (PNW).
- In 2013 spring (A-M-J), drought was declared for 9 counties in the southern Idaho. After 3 months, drought emergency was issued for 19 counties.
- In 2015 winter (J-F-M), PNW received historically low snowpack. Washington and Oregon governor declared state drought emergence in 2015 spring.
- Seasonal drought forecasting for the two drought events were applied using the proposed method.

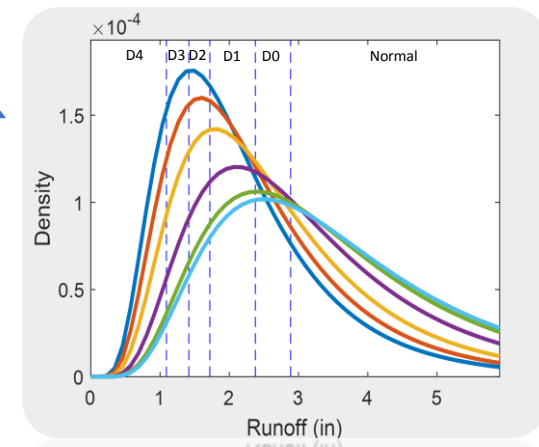
Data Assimilation System for initializing the Drought Forecast



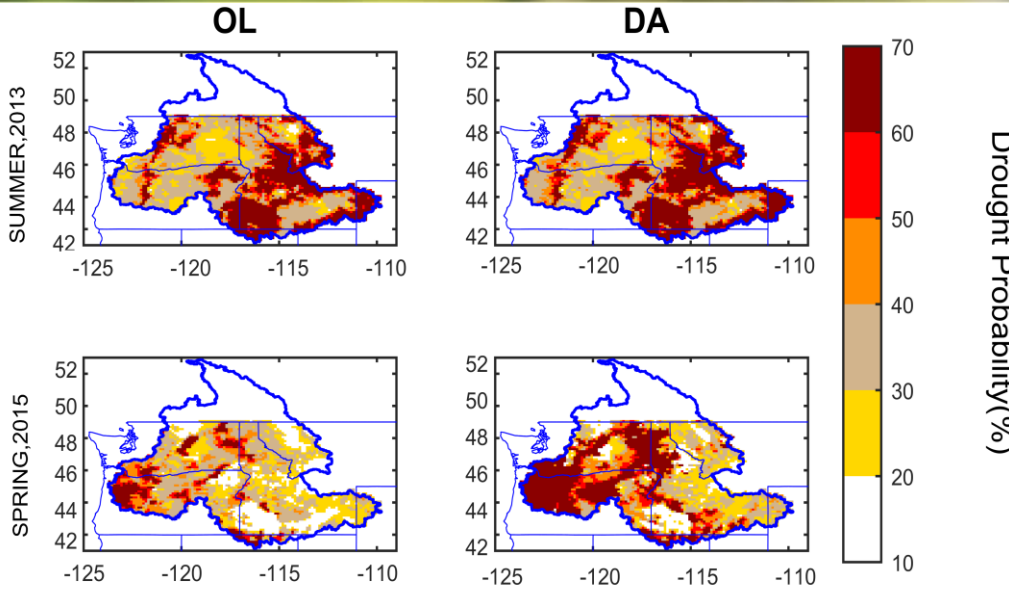
Madadgar and Moradkhani (2013)



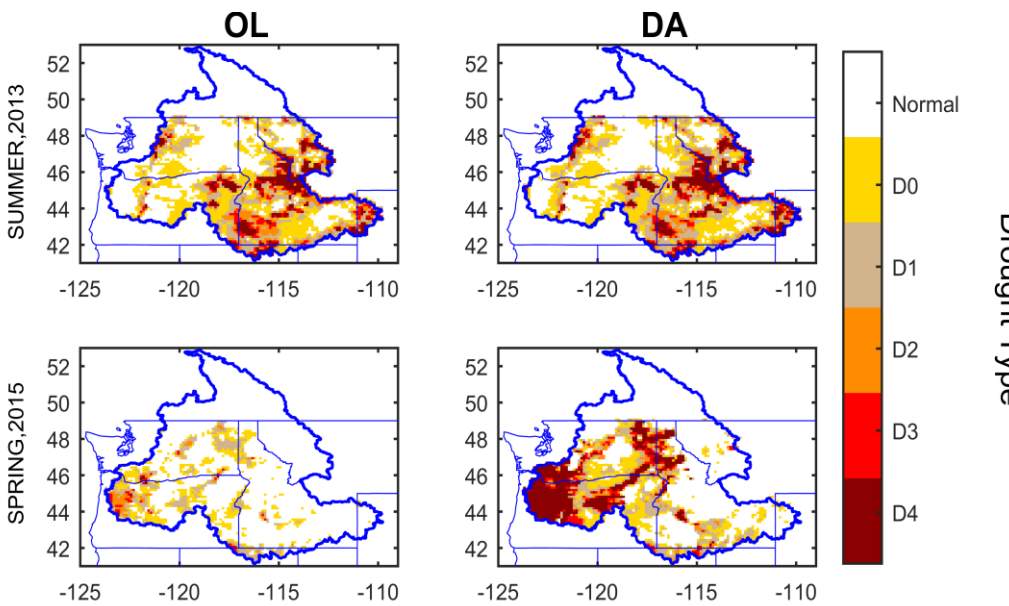
- Summer Runoff | Spring Drought=D4
- Summer Runoff | Spring Drought=D3
- Summer Runoff | Spring Drought=D2
- Summer Runoff | Spring Drought=D1
- Summer Runoff | Spring Drought=D0
- Summer Runoff | Spring Drought=Normal



Seasonal Drought Forecasting Results



Drought Probability(%)



Drought Type

- The results demonstrate the benefit of the proposed probabilistic forecasting system to aid the stakeholders for drought preparation and declaration, 3 to 6 months in advance

References:

- DeChant C.M., and H. Moradkhani (2014), Toward a Reliable Prediction of Seasonal Forecast Uncertainty: Addressing Model and Initial Condition Uncertainty with Ensemble Data Assimilation and Sequential Bayesian Combination, *Journal of Hydrology*, special issue on Ensemble Forecasting and data assimilation, 519, 2967-2977.
- DeChant, C., and H. Moradkhani, (2011), Improving the Characterization of Initial Condition for Ensemble Streamflow Prediction Using Data Assimilation, *Hydrol. Earth Syst. Sci.*, 15, 3399-3410, doi:10.5194/hess-15-3399.
- Madadgar, S. and H. Moradkhani (2013), A Bayesian Framework for Probabilistic Drought Forecasting, *Journal of Hydrometeorology*, special issue of Advances in Drought Monitoring, 14, 1685–1705, DOI: 10.1175/JHM-D-13-010.1
- Madadgar, S. and H. Moradkhani (2014), Improved Bayesian Multi-modeling: Integration of Copulas and Bayesian Model Averaging, *Water Resources Research*, 50, 9586–9603, DOI: 10.1002/2014WR015965.
- Moradkhani, H., C.M. DeChant and S. Sorooshian (2012), Evolution of Ensemble Data Assimilation for Uncertainty Quantification using the Particle Filter-Markov Chain Monte Carlo Method, *Water Resources Research*, 48, W12520, doi:10.1029/2012WR012144.